

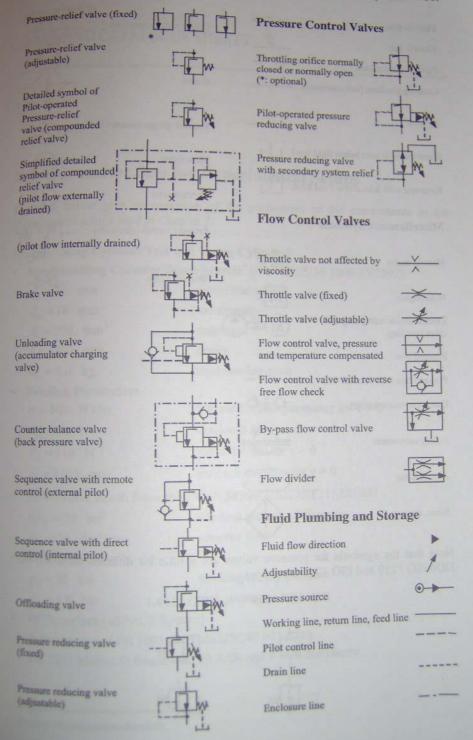
# APPENDIX A FLUID POWERS SYMBOLS

The symbols listed below are used to describe hydraulic system layouts (or circuits), and are based upon the German standard DIN-ISO 1219 (1978) and the international standard ISO 1219-1 (1991) for fluid power symbols.

#### Pumps, Motors, and Drives

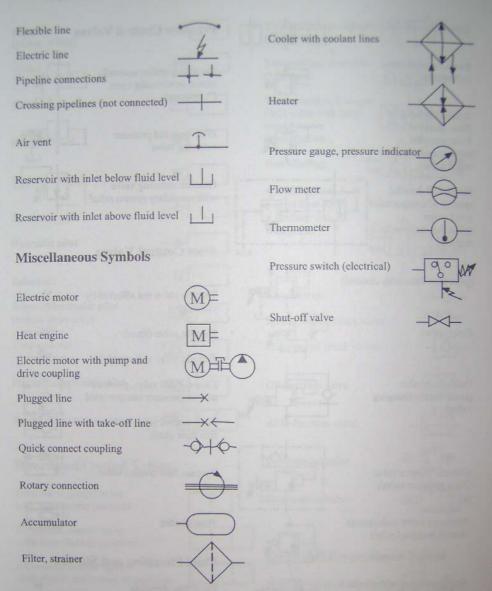
(spring returns the piston)

	Fixed Variable			
The state of the s	Titted Variable	Double acting actuator with double-ended rod		
Single direction pump	=0 =0		1	
Double direction pump	= = = = = = = = = = = = = = = = = = = =	Piston with adjustable and cushioning		
Single direction motor	=0 =0	Piston with fixed		
Double direction motor	=O =Ø	cushioning		
Single direction pump/motor with reversal of flow direction	=1 =20"	Telescopic, single acting actuator	- 4	
Single direction pump/motor with single flow direction	= = = = = = = = = = = = = = = = = = = =	Telescopic, double acting actuator		
Double direction pump/motor with two directions of flow	=D =B"	Pressure intensifier		
Hydrostatic drive, split system type	=0" 0=	Double acting actuator		
Hydrostatic drive, compact,	Cato	Differential actuator with oversize rod	FF	
Semi rotary actuator		Valve Control Mecha	alve Control Mechanisms	
		Undefined control	+	
Linear Actuators (Cylin	ders)		0	
		Hand lever	A	
Single acting ram		(rotary or linear)		
(load returns the ram)		Push button	<del>P</del>	
Single acting actuator (load returns the piston)		Foot lever	H	
Single acting actuator	TAAAATI	Cam roller		

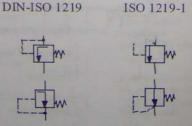


Plunger (piston or ball)	Two-position, four-port (4/2) valve	
Spring M	Two-position, five-port (5/2) valve	
Detent mechanism	Three-position, four-port (4/3) valve with fully closed centre	
Pressure relief	configuration Port labelling:	
Pressure applied	• working lines A, B P T	
Pneumatic pilot	pilot lines X, Y     pressure line P     tank line T	
Hydraulic pilot	W P T	
Solenoid	Check valve — — — — —	
Solenoid/hydraulic pilot (electro-hydraulic)	Spring-loaded check valve	
Torque motor	Pilot-loaded check valve	
Pneumatic/hydraulic pilot	OR function valve	
Spring centred W	AND function valve	
Directional Control Valves	Deceleration valve	
Directional control valve with two discrete positions	Deceleration valve	
Directional control valve with three discrete positions  Directional control valve with significant cross-over positions  Valve with two discrete positions and an infinite number of intermediate throttling positions	Servo and Proportional Valves  Proportional control pressure relief valve (with integral max. pressure limitation)	
Valve with three discrete positions and an infinite number of intermediate throttling positions	Pilot-operated directional proportional valve	
Two-position, two-port (2/2) valve  Two-position, three-port (3/2) valve	Four-way servo-valve with mechanical feedback, standard overlapping and	
[TT]	hydraulic zero PTT	

## 320 Appendix A. Fluid Power Symbols



Note that the symbols for pressure valves are a little bit different between the DIN-ISO 1219 and ISO 1219-1 versions:



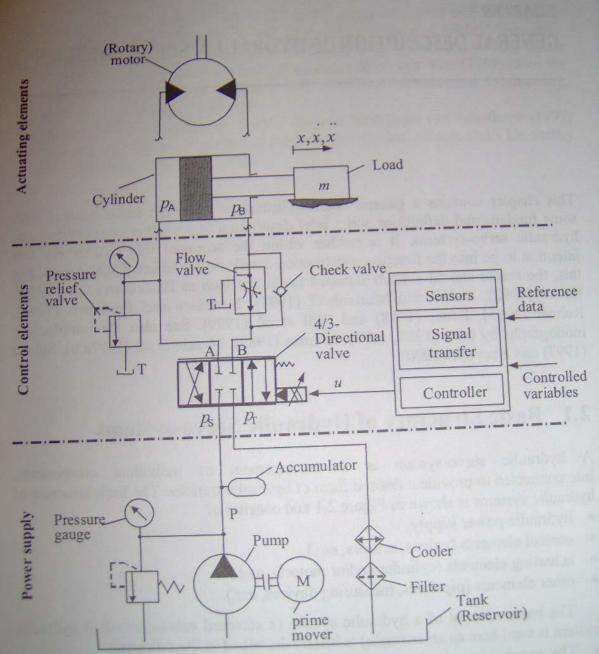


Figure 2.1. Basic structure of hydraulic systems (see Appendix A for hydraulic symbols)

#### 2.2.1 Valves

Valves are the most important mechanical (or electrical) link to the fluid interface in hydraulic systems.

#### 2.2.1.1 Valve Types

Basically there are four main categories of valves in hydraulics:

- (a) Pressure valves are used to control actuator force, and to determine and (pre)select pressure levels at which certain machine operations must occur:
  - Pressure-relief valves limit the maximum permissible system pressure, and divert some or all of the pump's flow to the tank when the pressure setting of the relief valve is reached. Pressure relief valves are "normally closed".
  - Pressure-reducing valves limit and maintain a constant downstream pressure (sub-circuit pressure) that is smaller than the system pressure regardless of pressure fluctuations in the main circuit upstream. Pressure reducing valves are "normally open".
- (b) Check valves are a very special type of directional control valve, as they only permit fluid flow in one direction while blocking flow in the reverse direction. They can be divided into unloaded or spring-loaded check valves, and check valves for logic operations (OR, AND).
- (c) Flow valves are used to control the rate of flow from one part of the hydraulic system to another, *i.e.*, they limit the maximum speed of cylinders and motors, limit the maximum power available to sub-circuits by controlling the flow of them, or proportionally divide or regulate the pump flow to various branches of the circuit.
- (d) Directional valves are used as multi-polar switches. Before the advent of servo and proportional valves they were used to control the direction of actuator motion, selected alternative control circuits, and performed logic control functions. Nowadays, however, proportionally variable controls allow infinitely adaptable and quickly variable setting of actuators with regard to force, speed and stroke position.

## 2.2.1.2 From Solenoid-valves to Servo-valves

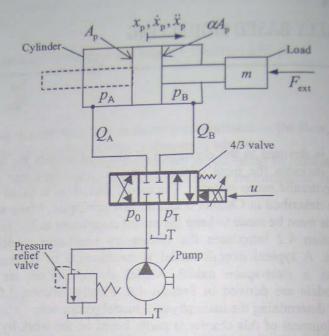


Figure 4.1. Valve-cylinder combination with power supply

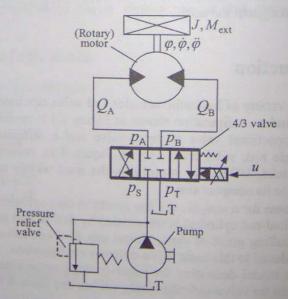
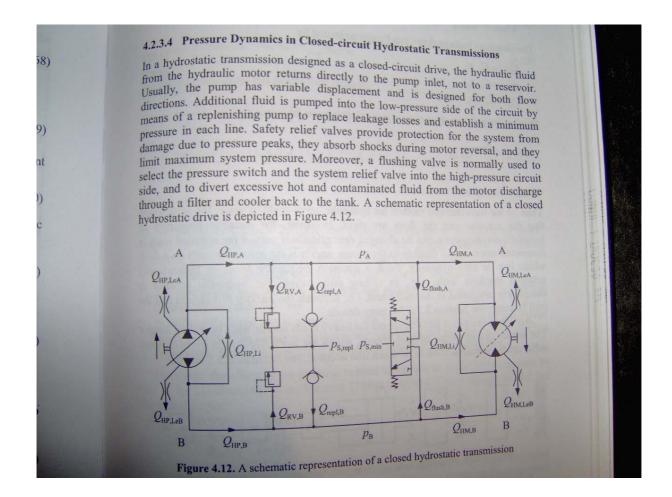
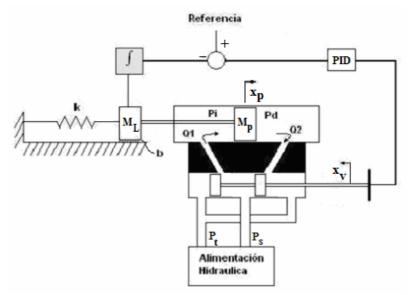


Figure 4.2. Valve-motor combination with power supply

## 4.1.1 Characterisation of Subsystems

Although a general characterisation of hydraulic servo-systems has already been given in Chapter 2, a more precise description, in view of the mathematical modelling of this system, is to be given, including the system boundary.





Control de posición a través de una válvula de 4 vías.