

# The index of symmetry

Carlos Olmos

FaMAF, Universidad Nacional de Córdoba

Rosario, 2 de agosto de 2012

- 1 Introduction
- 2 The index of symmetry
- 3 The dimension bound
- 4 Examples
- 5 Open questions

In this talk, based on joint work with Silvio Reggiani, we would like to draw the attention to some concept that we call *index of symmetry*  $i_s(M)$  of a Riemannian manifold  $M^n$

$$0 \leq i_s(M) \leq n$$

One has that  $M$  is symmetric if and only if  $i_s(M) = n$

We are, of course, interested on non-symmetric spaces with positive index of symmetry. In this case one has that  $i_s(M) \leq n - 2$ , as we will see later (in other words the *co-index of symmetry* is at least 2).

These examples are known homogenous spaces but endowed with a very particular Riemannian metric.

In this talk, based on joint work with Silvio Reggiani, we would like to draw the attention to some concept that we call *index of symmetry*  $i_s(M)$  of a Riemannian manifold  $M^n$

$$0 \leq i_s(M) \leq n$$

One has that  $M$  is symmetric if and only if  $i_s(M) = n$

We are, of course, interested on non-symmetric spaces with positive index of symmetry. In this case one has that  $i_s(M) \leq n - 2$ , as we will see later (in other words the *co-index of symmetry* is at least 2).

These examples are known homogenous spaces but endowed with a very particular Riemannian metric.

## Introduction

## The index of symmetry

## The dimension bound

## Examples

## Open questions

In this talk, based on joint work with Silvio Reggiani, we would like to draw the attention to some concept that we call *index of symmetry*  $i_s(M)$  of a Riemannian manifold  $M^n$

$$0 \leq i_s(M) \leq n$$

One has that  $M$  is symmetric if and only if  $i_s(M) = n$

We are, of course, interested on non-symmetric spaces with positive index of symmetry. In this case one has that  $i_s(M) \leq n - 2$ , as we will see later (in other words the *co-index of symmetry* is at least 2).

These examples are known homogenous spaces but endowed with a very particular Riemannian metric.

In this talk, based on joint work with Silvio Reggiani, we would like to draw the attention to some concept that we call *index of symmetry*  $i_{\mathfrak{g}}(M)$  of a Riemannian manifold  $M^n$

$$0 \leq i_{\mathfrak{g}}(M) \leq n$$

One has that  $M$  is symmetric if and only if  $i_{\mathfrak{g}}(M) = n$

We are, of course, interested on non-symmetric spaces with positive index of symmetry. In this case one has that  $i_{\mathfrak{g}}(M) \leq n - 2$ , as we will see later (in other words the *co-index of symmetry* is at least 2).

These examples are known homogenous spaces but endowed with a very particular Riemannian metric.

In this talk, based on joint work with Silvio Reggiani, we would like to draw the attention to some concept that we call *index of symmetry*  $i_5(M)$  of a Riemannian manifold  $M^n$

$$0 \leq i_5(M) \leq n$$

One has that  $M$  is symmetric if and only if  $i_5(M) = n$

We are, of course, interested on non-symmetric spaces with positive index of symmetry. In this case one has that  $i_5(M) \leq n - 2$ , as we will see later (in other words the *co-index of symmetry* is at least 2).

These examples are known homogenous spaces but endowed with a very particular Riemannian metric.

In this talk, based on joint work with Silvio Reggiani, we would like to draw the attention to some concept that we call *index of symmetry*  $i_{\mathfrak{g}}(M)$  of a Riemannian manifold  $M^n$

$$0 \leq i_{\mathfrak{g}}(M) \leq n$$

One has that  $M$  is symmetric if and only if  $i_{\mathfrak{g}}(M) = n$

We are, of course, interested on non-symmetric spaces with positive index of symmetry. In this case one has that  $i_{\mathfrak{g}}(M) \leq n - 2$ , as we will see later (in other words the *co-index of symmetry* is at least 2).

These examples are known homogenous spaces but endowed with a very particular Riemannian metric.



In this talk, based on joint work with Silvio Reggiani, we would like to draw the attention to some concept that we call *index of symmetry*  $i_{\mathfrak{g}}(M)$  of a Riemannian manifold  $M^n$

$$0 \leq i_{\mathfrak{g}}(M) \leq n$$

One has that  $M$  is symmetric if and only if  $i_{\mathfrak{g}}(M) = n$

We are, of course, interested on non-symmetric spaces with positive index of symmetry. In this case one has that  $i_{\mathfrak{g}}(M) \leq n - 2$ , as we will see later (in other words the *co-index of symmetry* is at least 2).

These examples are known homogenous spaces but endowed with a very particular Riemannian metric.

In this talk, based on joint work with Silvio Reggiani, we would like to draw the attention to some concept that we call *index of symmetry*  $i_{\mathfrak{g}}(M)$  of a Riemannian manifold  $M^n$

$$0 \leq i_{\mathfrak{g}}(M) \leq n$$

One has that  $M$  is symmetric if and only if  $i_{\mathfrak{g}}(M) = n$

We are, of course, interested on non-symmetric spaces with positive index of symmetry. In this case one has that  $i_{\mathfrak{g}}(M) \leq n - 2$ , as we will see later (in other words the *co-index of symmetry* is at least 2).

These examples are known homogenous spaces but endowed with a very particular Riemannian metric.

In this talk, based on joint work with Silvio Reggiani, we would like to draw the attention to some concept that we call *index of symmetry*  $i_{\mathfrak{g}}(M)$  of a Riemannian manifold  $M^n$

$$0 \leq i_{\mathfrak{g}}(M) \leq n$$

One has that  $M$  is symmetric if and only if  $i_{\mathfrak{g}}(M) = n$

We are, of course, interested on non-symmetric spaces with positive index of symmetry. In this case one has that  $i_{\mathfrak{g}}(M) \leq n - 2$ , as we will see later (in other words the *co-index of symmetry* is at least 2).

These examples are known homogenous spaces but endowed with a very particular Riemannian metric.

We are able to classify the spaces with small co-index of symmetry, after proving a bound on the dimension  $n$  of the space, for a fixed positive co-index of symmetry  $k$  (for irreducible spaces, since the product by a symmetric space does not change the co-index of symmetry, but increases the dimension).

The concept of index of symmetry came out from the study of compact naturally reductive spaces such that the isotropy has non-trivial fixed vectors (and so the full isometry group is bigger than the presentation group). For such spaces it is not hard to prove that the index of symmetry is at least the dimension of the fixed vectors of the isotropy representation.

Recently, with Reggiani and Tamaru, we could prove the equality, if the space is (irreducible, non-symmetric) presented with the transvections.

We are able to classify the spaces with small co-index of symmetry, after proving a bound on the dimension  $n$  of the space, for a fixed positive co-index of symmetry  $k$  (for irreducible spaces, since the product by a symmetric space does not change the co-index of symmetry, but increases the dimension).

The concept of index of symmetry came out from the study of compact naturally reductive spaces such that the isotropy has non-trivial fixed vectors (and so the full isometry group is bigger than the presentation group). For such spaces it is not hard to prove that the index of symmetry is at least the dimension of the fixed vectors of the isotropy representation.

Recently, with Reggiani and Tamaru, we could prove the equality, if the space is (irreducible, non-symmetric) presented with the transvections.

We are able to classify the spaces with small co-index of symmetry, after proving a bound on the dimension  $n$  of the space, for a fixed positive co-index of symmetry  $k$  (for irreducible spaces, since the product by a symmetric space does not change the co-index of symmetry, but increases the dimension).

The concept of index of symmetry came out from the study of compact naturally reductive spaces such that the isotropy has non-trivial fixed vectors (and so the full isometry group is bigger than the presentation group). For such spaces it is not hard to prove that the index of symmetry is at least the dimension of the fixed vectors of the isotropy representation.

Recently, with Reggiani and Tamaru, we could prove the equality, if the space is (irreducible, non-symmetric) presented with the transvections.

We are able to classify the spaces with small co-index of symmetry, after proving a bound on the dimension  $n$  of the space, for a fixed positive co-index of symmetry  $k$  (for irreducible spaces, since the product by a symmetric space does not change the co-index of symmetry, but increases the dimension).

The concept of index of symmetry came out from the study of compact naturally reductive spaces such that the isotropy has non-trivial fixed vectors (and so the full isometry group is bigger than the presentation group). For such spaces it is not hard to prove that the index of symmetry is at least the dimension of the fixed vectors of the isotropy representation.

Recently, with Reggiani and Tamaru, we could prove the equality, if the space is (irreducible, non-symmetric) presented with the transvections.

We are able to classify the spaces with small co-index of symmetry, after proving a bound on the dimension  $n$  of the space, for a fixed positive co-index of symmetry  $k$  (for irreducible spaces, since the product by a symmetric space does not change the co-index of symmetry, but increases the dimension).

The concept of index of symmetry came out from the study of compact naturally reductive spaces such that the isotropy has non-trivial fixed vectors (and so the full isometry group is bigger than the presentation group). For such spaces it is not hard to prove that the index of symmetry is at least the dimension of the fixed vectors of the isotropy representation.

Recently, with Reggiani and Tamaru, we could prove the equality, if the space is (irreducible, non-symmetric) presented with the transvections.



We are able to classify the spaces with small co-index of symmetry, after proving a bound on the dimension  $n$  of the space, for a fixed positive co-index of symmetry  $k$  (for irreducible spaces, since the product by a symmetric space does not change the co-index of symmetry, but increases the dimension).

The concept of index of symmetry came out from the study of compact naturally reductive spaces such that the isotropy has non-trivial fixed vectors (and so the full isometry group is bigger than the presentation group). For such spaces it is not hard to prove that the index of symmetry is at least the dimension of the fixed vectors of the isotropy representation.

Recently, with Reggiani and Tamaru, we could prove the equality, if the space is (irreducible, non-symmetric) presented with the transvections.

We are able to classify the spaces with small co-index of symmetry, after proving a bound on the dimension  $n$  of the space, for a fixed positive co-index of symmetry  $k$  (for irreducible spaces, since the product by a symmetric space does not change the co-index of symmetry, but increases the dimension).

The concept of index of symmetry came out from the study of compact naturally reductive spaces such that the isotropy has non-trivial fixed vectors (and so the full isometry group is bigger than the presentation group). For such spaces it is not hard to prove that the index of symmetry is at least the dimension of the fixed vectors of the isotropy representation.

Recently, with Reggiani and Tamaru, we could prove the equality, if the space is (irreducible, non-symmetric) presented with the transvections.

We are able to classify the spaces with small co-index of symmetry, after proving a bound on the dimension  $n$  of the space, for a fixed positive co-index of symmetry  $k$  (for irreducible spaces, since the product by a symmetric space does not change the co-index of symmetry, but increases the dimension).

The concept of index of symmetry came out from the study of compact naturally reductive spaces such that the isotropy has non-trivial fixed vectors (and so the full isometry group is bigger than the presentation group). For such spaces it is not hard to prove that the index of symmetry is at least the dimension of the fixed vectors of the isotropy representation.

Recently, with Reggiani and Tamaru, we could prove the equality, if the space is (irreducible, non-symmetric) presented with the transvections.

We are able to classify the spaces with small co-index of symmetry, after proving a bound on the dimension  $n$  of the space, for a fixed positive co-index of symmetry  $k$  (for irreducible spaces, since the product by a symmetric space does not change the co-index of symmetry, but increases the dimension).

The concept of index of symmetry came out from the study of compact naturally reductive spaces such that the isotropy has non-trivial fixed vectors (and so the full isometry group is bigger than the presentation group). For such spaces it is not hard to prove that the index of symmetry is at least the dimension of the fixed vectors of the isotropy representation.

Recently, with Reggiani and Tamaru, we could prove the equality, if the space is (irreducible, non-symmetric) presented with the transvections.

We are able to classify the spaces with small co-index of symmetry, after proving a bound on the dimension  $n$  of the space, for a fixed positive co-index of symmetry  $k$  (for irreducible spaces, since the product by a symmetric space does not change the co-index of symmetry, but increases the dimension).

The concept of index of symmetry came out from the study of compact naturally reductive spaces such that the isotropy has non-trivial fixed vectors (and so the full isometry group is bigger than the presentation group). For such spaces it is not hard to prove that the index of symmetry is at least the dimension of the fixed vectors of the isotropy representation.

Recently, with Reggiani and Tamaru, we could prove the equality, if the space is (irreducible, non-symmetric) presented with the transvections.

We are able to classify the spaces with small co-index of symmetry, after proving a bound on the dimension  $n$  of the space, for a fixed positive co-index of symmetry  $k$  (for irreducible spaces, since the product by a symmetric space does not change the co-index of symmetry, but increases the dimension).

The concept of index of symmetry came out from the study of compact naturally reductive spaces such that the isotropy has non-trivial fixed vectors (and so the full isometry group is bigger than the presentation group). For such spaces it is not hard to prove that the index of symmetry is at least the dimension of the fixed vectors of the isotropy representation.

Recently, with Reggiani and Tamaru, we could prove the equality, if the space is (irreducible, non-symmetric) presented with the transvections.

We are able to classify the spaces with small co-index of symmetry, after proving a bound on the dimension  $n$  of the space, for a fixed positive co-index of symmetry  $k$  (for irreducible spaces, since the product by a symmetric space does not change the co-index of symmetry, but increases the dimension).

The concept of index of symmetry came out from the study of compact naturally reductive spaces such that the isotropy has non-trivial fixed vectors (and so the full isometry group is bigger than the presentation group). For such spaces it is not hard to prove that the index of symmetry is at least the dimension of the fixed vectors of the isotropy representation.

Recently, with Reggiani and Tamaru, we could prove the equality, if the space is (irreducible, non-symmetric) presented with the transvections.

We are able to classify the spaces with small co-index of symmetry, after proving a bound on the dimension  $n$  of the space, for a fixed positive co-index of symmetry  $k$  (for irreducible spaces, since the product by a symmetric space does not change the co-index of symmetry, but increases the dimension).

The concept of index of symmetry came out from the study of compact naturally reductive spaces such that the isotropy has non-trivial fixed vectors (and so the full isometry group is bigger than the presentation group). For such spaces it is not hard to prove that the index of symmetry is at least the dimension of the fixed vectors of the isotropy representation.

Recently, with Reggiani and Tamaru, we could prove the equality, if the space is (irreducible, non-symmetric) presented with the transvections.



Introduction

The index of  
symmetry

The dimension  
bound

Examples

Open questions

The subjects of this talk may be regarded as an effort to explore Riemannian manifolds that are symmetric up to some defect (in the hope of finding distinguished non-symmetric homogeneous manifolds).

In some sense, our philosophy is in the direction of the concept of co-polarity by Claudio Gorodski, that measures how a representation, orbit like, differ from a symmetric (isotropy) representation (and also we try to classify those spaces when the defect is small).

The subjects of this talk may be regarded as an effort to explore Riemannian manifolds that are symmetric up to some defect (in the hope of finding distinguished non-symmetric homogeneous manifolds).

In some sense, our philosophy is in the direction of the concept of co-polarity by Claudio Gorodski, that measures how a representation, orbit like, differ from a symmetric (isotropy) representation (and also we try to classify those spaces when the defect is small).

The subjects of this talk may be regarded as an effort to explore Riemannian manifolds that are symmetric up to some defect (in the hope of finding distinguished non-symmetric homogeneous manifolds).

In some sense, our philosophy is in the direction of the concept of co-polarity by Claudio Gorodski, that measures how a representation, orbit like, differ from a symmetric (isotropy) representation (and also we try to classify those spaces when the defect is small).

The subjects of this talk may be regarded as an effort to explore Riemannian manifolds that are symmetric up to some defect (in the hope of finding distinguished non-symmetric homogeneous manifolds).

In some sense, our philosophy is in the direction of the concept of co-polarity by Claudio Gorodski, that measures how a representation, orbit like, differ from a symmetric (isotropy) representation (and also we try to classify those spaces when the defect is small).

The subjects of this talk may be regarded as an effort to explore Riemannian manifolds that are symmetric up to some defect (in the hope of finding distinguished non-symmetric homogeneous manifolds).

In some sense, our philosophy is in the direction of the concept of co-polarity by Claudio Gorodski, that measures how a representation, orbit like, differ from a symmetric (isotropy) representation (and also we try to classify those spaces when the defect is small).

The subjects of this talk may be regarded as an effort to explore Riemannian manifolds that are symmetric up to some defect (in the hope of finding distinguished non-symmetric homogeneous manifolds).

In some sense, our philosophy is in the direction of the concept of co-polarity by Claudio Gorodski, that measures how a representation, orbit like, differ from a symmetric (isotropy) representation (and also we try to classify those spaces when the defect is small).

## The index of symmetry.

Let  $M^n$  be a Riemannian manifold and denote by  $\mathfrak{K}(M)$  the algebra of global Killing fields on  $M$ .

For  $q \in M$ , let us define the Cartan subspace  $\mathfrak{p}^q$  at  $q$ , by

$$\mathfrak{p}^q := \{X \in \mathfrak{K}(M) : (\nabla X)_q = 0\}$$

The symmetric isotropy algebra at  $q$  is defined by

$$\mathfrak{k}^q := \{[X, Y] : X, Y \in \mathfrak{p}^q\}$$

Observe that  $\mathfrak{k}^q$  is contained in the (full) isotropy subalgebra  $\mathfrak{K}_q(M)$ . In fact, if  $X, Y \in \mathfrak{p}^q$ ,  $[X, Y]_q = (\nabla_X Y)_q - (\nabla_Y X)_q = 0$ . Moreover, since  $\mathfrak{p}^q$  is left invariant by the isotropy at  $q$ ,

$$\mathfrak{g}^q := \mathfrak{k}^q \oplus \mathfrak{p}^q$$

is an involutive Lie algebra.



The symmetric isotropy algebra at  $q$  is defined by

$$\mathfrak{k}^q := \{[X, Y] : X, Y \in \mathfrak{p}^q\}$$

Observe that  $\mathfrak{k}^q$  is contained in the (full) isotropy subalgebra  $\mathfrak{K}_q(M)$ . In fact, if  $X, Y \in \mathfrak{p}^q$ ,  $[X, Y]_q = (\nabla_X Y)_q - (\nabla_Y X)_q = 0$ . Moreover, since  $\mathfrak{p}^q$  is left invariant by the isotropy at  $q$ ,

$$\mathfrak{g}^q := \mathfrak{k}^q \oplus \mathfrak{p}^q$$

is an involutive Lie algebra.

The symmetric isotropy algebra at  $q$  is defined by

$$\mathfrak{k}^q := \{[X, Y] : X, Y \in \mathfrak{p}^q\}$$

Observe that  $\mathfrak{k}^q$  is contained in the (full) isotropy subalgebra  $\mathfrak{K}_q(M)$ . In fact, if  $X, Y \in \mathfrak{p}^q$ ,  $[X, Y]_q = (\nabla_X Y)_q - (\nabla_Y X)_q = 0$ . Moreover, since  $\mathfrak{p}^q$  is left invariant by the isotropy at  $q$ ,

$$\mathfrak{g}^q := \mathfrak{k}^q \oplus \mathfrak{p}^q$$

is an involutive Lie algebra.

The symmetric subspace at  $q$ ,  $\mathfrak{s}_q \subset T_qM$ , is defined by

$$\mathfrak{s}_q := \{X.q : X \in \mathfrak{p}^q\} = \mathfrak{p}^q.q$$

The local version, involving local Killing fields, can be equivalently defined as follows (from a joint work with Sergio Console, PAMS 09)

$$\mathfrak{s}_q^{loc} := \{v \in T_qM : \nabla_v^k R = 0, k = 0, \dots, n + \frac{1}{2}n(n-1)\},$$

The symmetric subspace at  $q$ ,  $\mathfrak{s}_q \subset T_q M$ , is defined by

$$\mathfrak{s}_q := \{X.q : X \in \mathfrak{p}^q\} = \mathfrak{p}^q.q$$

The local version, involving local Killing fields, can be equivalently defined as follows (from a joint work with [Sergio Console](#), PAMS 09)

$$\mathfrak{s}_q^{loc} := \{v \in T_q M : \nabla_v^k R = 0, k = 0, \dots, n + \frac{1}{2}n(n-1)\},$$

The symmetric subspace at  $q$ ,  $\mathfrak{s}_q \subset T_qM$ , is defined by

$$\mathfrak{s}_q := \{X.q : X \in \mathfrak{p}^q\} = \mathfrak{p}^q.q$$

The local version, involving local Killing fields, can be equivalently defined as follows (from a joint work with [Sergio Console](#), PAMS 09)

$$\mathfrak{s}_q^{loc} := \{v \in T_qM : \nabla_v^k R = 0, k = 0, \dots, n + \frac{1}{2}n(n-1)\},$$

The symmetric subspace at  $q$ ,  $\mathfrak{s}_q \subset T_q M$ , is defined by

$$\mathfrak{s}_q := \{X.q : X \in \mathfrak{p}^q\} = \mathfrak{p}^q.q$$

The local version, involving local Killing fields, can be equivalently defined as follows (from a joint work with [Sergio Console](#), PAMS 09)

$$\mathfrak{s}_q^{loc} := \{v \in T_q M : \nabla_v^k R = 0, k = 0, \dots, n + \frac{1}{2}n(n-1)\},$$

For dealing with the distribution  $\mathfrak{g} \mapsto \mathfrak{g}^q$  one needs to regard Killing fields as parallel sections of the so called canonical (vector) bundle over  $M$ ,

$$TM \oplus \Lambda^2(TM) \simeq TM \oplus \mathfrak{so}(TM)$$

where the connection  $\bar{\nabla}$  in  $TM \oplus \mathfrak{so}(TM)$  is given by

$$\bar{\nabla}_Y(Z, B) = (\nabla_Y Z - BY, \nabla_Y B - R_{Y,Z})$$

The bijection is given by

$$Z \leftrightarrow (Z, \nabla Z)$$

The curvature tensor  $\bar{R}$  of  $\bar{\nabla}$  is given by

$$\bar{R}_{X,Y}(Z, B) = (0, (\nabla_Z R)_{X,Y} - (B.R)_{X,Y})$$

where  $B$  acts on a tensor as a derivation.

For dealing with the distribution  $g \mapsto \mathfrak{g}^g$  one needs to regard Killing fields as parallel sections of the so called canonical (vector) bundle over  $M$ ,

$$TM \oplus \Lambda^2(TM) \simeq TM \oplus \mathfrak{so}(TM)$$

where the connection  $\bar{\nabla}$  in  $TM \oplus \mathfrak{so}(TM)$  is given by

$$\bar{\nabla}_Y(Z, B) = (\nabla_Y Z - BY, \nabla_Y B - R_{Y,Z})$$

The bijection is given by

$$Z \leftrightarrow (Z, \nabla Z)$$

The curvature tensor  $\bar{R}$  of  $\bar{\nabla}$  is given by

$$\bar{R}_{X,Y}(Z, B) = (0, (\nabla_Z R)_{X,Y} - (B.R)_{X,Y})$$

where  $B$  acts on a tensor as a derivation.



For dealing with the distribution  $q \mapsto \mathfrak{s}^q$  one needs to regard Killing fields as parallel sections of the so called canonical (vector) bundle over  $M$ ,

$$TM \oplus \Lambda^2(TM) \simeq TM \oplus \mathfrak{so}(TM)$$

where the connection  $\bar{\nabla}$  in  $TM \oplus \mathfrak{so}(TM)$  is given by

$$\bar{\nabla}_Y(Z, B) = (\nabla_Y Z - BY, \nabla_Y B - R_{Y,Z})$$

The bijection is given by

$$Z \leftrightarrow (Z, \nabla Z)$$

The curvature tensor  $\bar{R}$  of  $\bar{\nabla}$  is given by

$$\bar{R}_{X,Y}(Z, B) = (0, (\nabla_Z R)_{X,Y} - (B.R)_{X,Y})$$

where  $B$  acts on a tensor as a derivation.

For dealing with the distribution  $q \mapsto \mathfrak{s}^q$  one needs to regard Killing fields as parallel sections of the so called canonical (vector) bundle over  $M$ ,

$$TM \oplus \Lambda^2(TM) \simeq TM \oplus \mathfrak{so}(TM)$$

where the connection  $\bar{\nabla}$  in  $TM \oplus \mathfrak{so}(TM)$  is given by

$$\bar{\nabla}_Y(Z, B) = (\nabla_Y Z - BY, \nabla_Y B - R_{Y,Z})$$

The bijection is given by

$$Z \leftrightarrow (Z, \nabla Z)$$

The curvature tensor  $\bar{R}$  of  $\bar{\nabla}$  is given by

$$\bar{R}_{X,Y}(Z, B) = (0, (\nabla_Z R)_{X,Y} - (B.R)_{X,Y})$$

where  $B$  acts on a tensor as a derivation.

For dealing with the distribution  $q \mapsto \mathfrak{s}^q$  one needs to regard Killing fields as parallel sections of the so called canonical (vector) bundle over  $M$ ,

$$TM \oplus \Lambda^2(TM) \simeq TM \oplus \mathfrak{so}(TM)$$

where the connection  $\bar{\nabla}$  in  $TM \oplus \mathfrak{so}(TM)$  is given by

$$\bar{\nabla}_Y(Z, B) = (\nabla_Y Z - BY, \nabla_Y B - R_{Y,Z})$$

The bijection is given by

$$Z \leftrightarrow (Z, \nabla Z)$$

The curvature tensor  $\bar{R}$  of  $\bar{\nabla}$  is given by

$$\bar{R}_{X,Y}(Z, B) = (0, (\nabla_Z R)_{X,Y} - (B.R)_{X,Y})$$

where  $B$  acts on a tensor as a derivation.

For dealing with the distribution  $q \mapsto \mathfrak{s}^q$  one needs to regard Killing fields as parallel sections of the so called canonical (vector) bundle over  $M$ ,

$$TM \oplus \Lambda^2(TM) \simeq TM \oplus \mathfrak{so}(TM)$$

where the connection  $\bar{\nabla}$  in  $TM \oplus \mathfrak{so}(TM)$  is given by

$$\bar{\nabla}_Y(Z, B) = (\nabla_Y Z - BY, \nabla_Y B - R_{Y,Z})$$

The bijection is given by

$$Z \leftrightarrow (Z, \nabla Z)$$

The curvature tensor  $\bar{R}$  of  $\bar{\nabla}$  is given by

$$\bar{R}_{X,Y}(Z, B) = (0, (\nabla_Z R)_{X,Y} - (B \cdot R)_{X,Y})$$

where  $B$  acts on a tensor as a derivation.

For dealing with the distribution  $q \mapsto \mathfrak{s}^q$  one needs to regard Killing fields as parallel sections of the so called canonical (vector) bundle over  $M$ ,

$$TM \oplus \Lambda^2(TM) \simeq TM \oplus \mathfrak{so}(TM)$$

where the connection  $\bar{\nabla}$  in  $TM \oplus \mathfrak{so}(TM)$  is given by

$$\bar{\nabla}_Y(Z, B) = (\nabla_Y Z - BY, \nabla_Y B - R_{Y,Z})$$

The bijection is given by

$$Z \leftrightarrow (Z, \nabla Z)$$

The curvature tensor  $\bar{R}$  of  $\bar{\nabla}$  is given by

$$\bar{R}_{X,Y}(Z, B) = (0, (\nabla_Z R)_{X,Y} - (B.R)_{X,Y})$$

where  $B$  acts on a tensor as a derivation.

For dealing with the distribution  $q \mapsto \mathfrak{s}^q$  one needs to regard Killing fields as parallel sections of the so called canonical (vector) bundle over  $M$ ,

$$TM \oplus \Lambda^2(TM) \simeq TM \oplus \mathfrak{so}(TM)$$

where the connection  $\bar{\nabla}$  in  $TM \oplus \mathfrak{so}(TM)$  is given by

$$\bar{\nabla}_Y(Z, B) = (\nabla_Y Z - BY, \nabla_Y B - R_{Y,Z})$$

The bijection is given by

$$Z \leftrightarrow (Z, \nabla Z)$$

The curvature tensor  $\bar{R}$  of  $\bar{\nabla}$  is given by

$$\bar{R}_{X,Y}(Z, B) = (0, (\nabla_Z R)_{X,Y} - (B.R)_{X,Y})$$

where  $B$  acts on a tensor as a derivation.

For dealing with the distribution  $q \mapsto \mathfrak{s}^q$  one needs to regard Killing fields as parallel sections of the so called canonical (vector) bundle over  $M$ ,

$$TM \oplus \Lambda^2(TM) \simeq TM \oplus \mathfrak{so}(TM)$$

where the connection  $\bar{\nabla}$  in  $TM \oplus \mathfrak{so}(TM)$  is given by

$$\bar{\nabla}_Y(Z, B) = (\nabla_Y Z - BY, \nabla_Y B - R_{Y,Z})$$

The bijection is given by

$$Z \leftrightarrow (Z, \nabla Z)$$

The curvature tensor  $\bar{R}$  of  $\bar{\nabla}$  is given by

$$\bar{R}_{X,Y}(Z, B) = (0, (\nabla_Z R)_{X,Y} - (B.R)_{X,Y})$$

where  $B$  acts on a tensor as a derivation.

## Lemma

Let  $X, Y \in \mathfrak{p}^q$ , regarded as Killing fields, and let  $Z$  be an arbitrary tangent field of  $M$ . Then

$$R_{X(q), Y(q)}Z(q) = -[[X, Y], Z](q)$$

Let  $q \in M$  and assume that the index of symmetry at  $q$  is positive, i.e.  $\dim \mathfrak{s}_q > 0$ . Let us consider the Lie subalgebra  $\mathfrak{g}^q$  of the full isometry algebra. One has that

$$\mathfrak{g}^q = \mathfrak{k}^q \oplus \mathfrak{p}^q$$

is an involutive Lie algebra. Let  $G^q$  be its associated Lie subgroup of  $I(M)$ . One has that the orbit  $G^q \cdot q$  is a global symmetric space, which is a totally geodesic immersed manifold of  $M$ .



## Lemma

Let  $X, Y \in \mathfrak{p}^q$ , regarded as Killing fields, and let  $Z$  be an arbitrary tangent field of  $M$ . Then

$$R_{X(q), Y(q)}Z(q) = -[[X, Y], Z](q)$$

Let  $q \in M$  and assume that the index of symmetry at  $q$  is positive, i.e.  $\dim \mathfrak{s}_q > 0$ . Let us consider the Lie subalgebra  $\mathfrak{g}^q$  of the full isometry algebra. One has that

$$\mathfrak{g}^q = \mathfrak{k}^q \oplus \mathfrak{p}^q$$

is an involutive Lie algebra. Let  $G^q$  be its associated Lie subgroup of  $I(M)$ . One has that the orbit  $G^q \cdot q$  is a global symmetric space, which is a totally geodesic immersed manifold of  $M$ .

## Lemma

Let  $X, Y \in \mathfrak{p}^q$ , regarded as Killing fields, and let  $Z$  be an arbitrary tangent field of  $M$ . Then

$$R_{X(q), Y(q)}Z(q) = -[[X, Y], Z](q)$$

Let  $q \in M$  and assume that the index of symmetry at  $q$  is positive, i.e.  $\dim \mathfrak{s}_q > 0$ . Let us consider the Lie subalgebra  $\mathfrak{g}^q$  of the full isometry algebra. One has that

$$\mathfrak{g}^q = \mathfrak{k}^q \oplus \mathfrak{p}^q$$

is an involutive Lie algebra. Let  $G^q$  be its associated Lie subgroup of  $I(M)$ . One has that the orbit  $G^q \cdot q$  is a global symmetric space, which is a totally geodesic immersed manifold of  $M$ .

## Lemma

Let  $X, Y \in \mathfrak{p}^q$ , regarded as Killing fields, and let  $Z$  be an arbitrary tangent field of  $M$ . Then

$$R_{X(q), Y(q)}Z(q) = -[[X, Y], Z](q)$$

Let  $q \in M$  and assume that the index of symmetry at  $q$  is positive, i.e.  $\dim \mathfrak{s}_q > 0$ . Let us consider the Lie subalgebra  $\mathfrak{g}^q$  of the full isometry algebra. One has that

$$\mathfrak{g}^q = \mathfrak{k}^q \oplus \mathfrak{p}^q$$

is an involutive Lie algebra. Let  $G^q$  be its associated Lie subgroup of  $I(M)$ . One has that the orbit  $G^q \cdot q$  is a global symmetric space, which is a totally geodesic immersed manifold of  $M$ .

## Lemma

Let  $X, Y \in \mathfrak{p}^q$ , regarded as Killing fields, and let  $Z$  be an arbitrary tangent field of  $M$ . Then

$$R_{X(q), Y(q)}Z(q) = -[[X, Y], Z](q)$$

Let  $q \in M$  and assume that the index of symmetry at  $q$  is positive, i.e.  $\dim \mathfrak{s}_q > 0$ . Let us consider the Lie subalgebra  $\mathfrak{g}^q$  of the full isometry algebra. One has that

$$\mathfrak{g}^q = \mathfrak{k}^q \oplus \mathfrak{p}^q$$

is an involutive Lie algebra. Let  $G^q$  be its associated Lie subgroup of  $I(M)$ . One has that the orbit  $G^q \cdot q$  is a global symmetric space, which is a totally geodesic immersed manifold of  $M$ .

## Lemma

Let  $X, Y \in \mathfrak{p}^q$ , regarded as Killing fields, and let  $Z$  be an arbitrary tangent field of  $M$ . Then

$$R_{X(q), Y(q)}Z(q) = -[[X, Y], Z](q)$$

Let  $q \in M$  and assume that the index of symmetry at  $q$  is positive, i.e.  $\dim \mathfrak{s}_q > 0$ . Let us consider the Lie subalgebra  $\mathfrak{g}^q$  of the full isometry algebra. One has that

$$\mathfrak{g}^q = \mathfrak{k}^q \oplus \mathfrak{p}^q$$

is an involutive Lie algebra. Let  $G^q$  be its associated Lie subgroup of  $I(M)$ . One has that the orbit  $G^q \cdot q$  is a **global symmetric space**, which is a totally geodesic immersed manifold of  $M$ .

## Lemma

Let  $X, Y \in \mathfrak{p}^q$ , regarded as Killing fields, and let  $Z$  be an arbitrary tangent field of  $M$ . Then

$$R_{X(q), Y(q)}Z(q) = -[[X, Y], Z](q)$$

Let  $q \in M$  and assume that the index of symmetry at  $q$  is positive, i.e.  $\dim \mathfrak{s}_q > 0$ . Let us consider the Lie subalgebra  $\mathfrak{g}^q$  of the full isometry algebra. One has that

$$\mathfrak{g}^q = \mathfrak{k}^q \oplus \mathfrak{p}^q$$

is an involutive Lie algebra. Let  $G^q$  be its associated Lie subgroup of  $I(M)$ . One has that the orbit  $G^q \cdot q$  is a **global symmetric space**, which is a totally geodesic immersed manifold of  $M$ .

## Lemma

Let  $X, Y \in \mathfrak{p}^q$ , regarded as Killing fields, and let  $Z$  be an arbitrary tangent field of  $M$ . Then

$$R_{X(q), Y(q)}Z(q) = -[[X, Y], Z](q)$$

Let  $q \in M$  and assume that the index of symmetry at  $q$  is positive, i.e.  $\dim \mathfrak{s}_q > 0$ . Let us consider the Lie subalgebra  $\mathfrak{g}^q$  of the full isometry algebra. One has that

$$\mathfrak{g}^q = \mathfrak{k}^q \oplus \mathfrak{p}^q$$

is an involutive Lie algebra. Let  $G^q$  be its associated Lie subgroup of  $I(M)$ . One has that the orbit  $G^q \cdot q$  is a **global symmetric space**, which is a totally geodesic immersed manifold of  $M$ .

## Proposition

If  $M$  is compact, then  $G^q$  acts almost effectively on the orbit  $G^q.q$ .

Identify  $T_q(G^q.q) = \mathfrak{s}_q \simeq \mathfrak{p}^q$  and decompose

$$\mathfrak{p}^q = \mathfrak{p}_0 \oplus \mathfrak{p}_1 \oplus \dots \oplus \mathfrak{p}_r$$

where  $\mathfrak{p}_0$  corresponds to the Euclidean factor and  $\mathfrak{p}_i$  corresponds to the irreducible factors, in the de Rham local decomposition of the orbit  $G^q.q$  ( $i = 1, \dots, r$ ).

Let, for  $j = 0, \dots, r$ ,

$$\mathfrak{k}_j := [\mathfrak{p}_j, \mathfrak{p}_j].$$

Then

$$\mathfrak{g}_j = \mathfrak{k}_j \oplus \mathfrak{p}_j$$

is a subalgebra of  $\mathfrak{g}^q$ .

Introduction

The index of symmetry

The dimension bound

Examples

Open questions



## Proposition

If  $M$  is compact, then  $G^q$  acts almost effectively on the orbit  $G^q.q$ .

Identify  $T_q(G^q.q) = \mathfrak{s}_q \simeq \mathfrak{p}^q$  and decompose

$$\mathfrak{p}^q = \mathfrak{p}_0 \oplus \mathfrak{p}_1 \oplus \dots \oplus \mathfrak{p}_r$$

where  $\mathfrak{p}_0$  corresponds to the Euclidean factor and  $\mathfrak{p}_i$  corresponds to the irreducible factors, in the de Rham local decomposition of the orbit  $G^q.q$  ( $i = 1, \dots, r$ ).

Let, for  $j = 0, \dots, r$ ,

$$\mathfrak{k}_j := [\mathfrak{p}_j, \mathfrak{p}_j].$$

Then

$$\mathfrak{g}_j = \mathfrak{k}_j \oplus \mathfrak{p}_j$$

is a subalgebra of  $\mathfrak{g}^q$ .

Introduction

The index of symmetry

The dimension bound

Examples

Open questions

## Proposition

If  $M$  is compact, then  $G^q$  acts almost effectively on the orbit  $G^q.q$ .

Identify  $T_q(G^q.q) = \mathfrak{s}_q \simeq \mathfrak{p}^q$  and decompose

$$\mathfrak{p}^q = \mathfrak{p}_0 \oplus \mathfrak{p}_1 \oplus \dots \oplus \mathfrak{p}_r$$

where  $\mathfrak{p}_0$  corresponds to the Euclidean factor and  $\mathfrak{p}_i$  corresponds to the irreducible factors, in the de Rham local decomposition of the orbit  $G^q.q$  ( $i = 1, \dots, r$ ).

Let, for  $j = 0, \dots, r$ ,

$$\mathfrak{k}_j := [\mathfrak{p}_j, \mathfrak{p}_j].$$

Then

$$\mathfrak{g}_j = \mathfrak{k}_j \oplus \mathfrak{p}_j$$

is a subalgebra of  $\mathfrak{g}^q$ .

Introduction

The index of symmetry

The dimension bound

Examples

Open questions

## Proposition

If  $M$  is compact, then  $G^q$  acts almost effectively on the orbit  $G^q \cdot q$ .

Identify  $T_q(G^q \cdot q) = \mathfrak{s}_q \simeq \mathfrak{p}^q$  and decompose

$$\mathfrak{p}^q = \mathfrak{p}_0 \oplus \mathfrak{p}_1 \oplus \dots \oplus \mathfrak{p}_r$$

where  $\mathfrak{p}_0$  corresponds to the Euclidean factor and  $\mathfrak{p}_i$  corresponds to the irreducible factors, in the de Rham local decomposition of the orbit  $G^q \cdot q$  ( $i = 1, \dots, r$ ).

Let, for  $j = 0, \dots, r$ ,

$$\mathfrak{k}_j := [\mathfrak{p}_j, \mathfrak{p}_j].$$

Then

$$\mathfrak{g}_j = \mathfrak{k}_j \oplus \mathfrak{p}_j$$

is a subalgebra of  $\mathfrak{g}^q$ .

Introduction

The index of symmetry

The dimension bound

Examples

Open questions

## Proposition

If  $M$  is compact, then  $G^q$  acts almost effectively on the orbit  $G^q.q$ .

Identify  $T_q(G^q.q) = \mathfrak{s}_q \simeq \mathfrak{p}^q$  and decompose

$$\mathfrak{p}^q = \mathfrak{p}_0 \oplus \mathfrak{p}_1 \oplus \dots \oplus \mathfrak{p}_r$$

where  $\mathfrak{p}_0$  corresponds to the Euclidean factor and  $\mathfrak{p}_i$  corresponds to the irreducible factors, in the de Rham local decomposition of the orbit  $G^q.q$  ( $i = 1, \dots, r$ ).

Let, for  $j = 0, \dots, r$ ,

$$\mathfrak{k}_j := [\mathfrak{p}_j, \mathfrak{p}_j].$$

Then

$$\mathfrak{g}_j = \mathfrak{k}_j \oplus \mathfrak{p}_j$$

is a subalgebra of  $\mathfrak{g}^q$ .

Introduction

The index of symmetry

The dimension bound

Examples

Open questions

But, if the action of  $G^q$  is not almost effective on the orbit  $G^q.q$ , we cannot conclude neither that  $\mathfrak{g}^q$  is spanned by  $\mathfrak{g}_0, \dots, \mathfrak{g}_r$

nor that these subalgebras are in a direct sum (and not even that  $\mathfrak{k}_0$  is trivial or that  $\mathfrak{g}_i$  are ideals).

The main point is that we do not know, in the **non-compact case**, that  $R_{p_i, p_j} = 0$ , for  $i \neq j$ , (only we know it is true for the restriction to the totally geodesic submanifold  $G^q.q$ ).

## Corollary

*If  $M$  is compact then  $\mathfrak{k}_0 = 0$ ,  $[\mathfrak{g}_i, \mathfrak{g}_j] = 0$ , if  $i \neq j$  and so  $\mathfrak{g}^q$  is the direct sum of the ideals  $\mathfrak{g}_1, \dots, \mathfrak{g}_s$ . Then*

$$G^q = G_0^q \times \dots \times G_r^q \quad (\text{almost direct product})$$

*where  $\text{Lie}(G_i^q) = \mathfrak{g}_i$ .*

But, if the action of  $G^q$  is not almost effective on the orbit  $G^q.q$ , we cannot conclude neither that  $\mathfrak{g}^q$  is spanned by  $\mathfrak{g}_0, \dots, \mathfrak{g}_r$

nor that these subalgebras are in a direct sum (and not even that  $\mathfrak{k}_0$  is trivial or that  $\mathfrak{g}_i$  are ideals).

The main point is that we do not know, in the **non-compact case**, that  $R_{p_i, p_j} = 0$ , for  $i \neq j$ , (only we know it is true for the restriction to the totally geodesic submanifold  $G^q.q$ ).

## Corollary

*If  $M$  is compact then  $\mathfrak{k}_0 = 0$ ,  $[\mathfrak{g}_i, \mathfrak{g}_j] = 0$ , if  $i \neq j$  and so  $\mathfrak{g}^q$  is the direct sum of the ideals  $\mathfrak{g}_1, \dots, \mathfrak{g}_s$ . Then*

$$G^q = G_0^q \times \dots \times G_r^q \quad (\text{almost direct product})$$

*where  $\text{Lie}(G_i^q) = \mathfrak{g}_i$ .*

But, if the action of  $G^q$  is not almost effective on the orbit  $G^q.q$ , we cannot conclude neither that  $\mathfrak{g}^q$  is spanned by  $\mathfrak{g}_0, \dots, \mathfrak{g}_r$

nor that these subalgebras are in a direct sum (and not even that  $\mathfrak{k}_0$  is trivial or that  $\mathfrak{g}_j$  are ideals).

The main point is that we do not know, in the **non-compact case**, that  $R_{p_i, p_j} = 0$ , for  $i \neq j$ , (only we know it is true for the restriction to the totally geodesic submanifold  $G^q.q$ ).

## Corollary

*If  $M$  is compact then  $\mathfrak{k}_0 = 0$ ,  $[\mathfrak{g}_i, \mathfrak{g}_j] = 0$ , if  $i \neq j$  and so  $\mathfrak{g}^q$  is the direct sum of the ideals  $\mathfrak{g}_1, \dots, \mathfrak{g}_s$ . Then*

$$G^q = G_0^q \times \dots \times G_r^q \quad (\text{almost direct product})$$

*where  $\text{Lie}(G_i^q) = \mathfrak{g}_i$ .*

But, if the action of  $G^q$  is not almost effective on the orbit  $G^q \cdot q$ , we cannot conclude neither that  $\mathfrak{g}^q$  is spanned by  $\mathfrak{g}_0, \dots, \mathfrak{g}_r$

nor that these subalgebras are in a direct sum (and not even that  $\mathfrak{k}_0$  is trivial or that  $\mathfrak{g}_i$  are ideals).

The main point is that we do not know, in the **non-compact case**, that  $R_{p_i, p_j} = 0$ , for  $i \neq j$ , (only we know it is true for the restriction to the totally geodesic submanifold  $G^q \cdot q$ ).

## Corollary

*If  $M$  is compact then  $\mathfrak{k}_0 = 0$ ,  $[\mathfrak{g}_i, \mathfrak{g}_j] = 0$ , if  $i \neq j$  and so  $\mathfrak{g}^q$  is the direct sum of the ideals  $\mathfrak{g}_1, \dots, \mathfrak{g}_s$ . Then*

$$G^q = G_0^q \times \dots \times G_r^q \quad (\text{almost direct product})$$

*where  $\text{Lie}(G_i^q) = \mathfrak{g}_i$ .*



But, if the action of  $G^q$  is not almost effective on the orbit  $G^q \cdot q$ , we cannot conclude neither that  $\mathfrak{g}^q$  is spanned by  $\mathfrak{g}_0, \dots, \mathfrak{g}_r$

nor that these subalgebras are in a direct sum (and not even that  $\mathfrak{k}_0$  is trivial or that  $\mathfrak{g}_i$  are ideals).

The main point is that we do not know, in the **non-compact case**, that  $R_{p_i, p_j} = 0$ , for  $i \neq j$ , (only we know it is true for the restriction to the totally geodesic submanifold  $G^q \cdot q$ ).

## Corollary

*If  $M$  is compact then  $\mathfrak{k}_0 = 0$ ,  $[\mathfrak{g}_i, \mathfrak{g}_j] = 0$ , if  $i \neq j$  and so  $\mathfrak{g}^q$  is the direct sum of the ideals  $\mathfrak{g}_1, \dots, \mathfrak{g}_s$ . Then*

$$G^q = G_0^q \times \dots \times G_r^q \quad (\text{almost direct product})$$

*where  $\text{Lie}(G_i^q) = \mathfrak{g}_i$ .*

But, if the action of  $G^q$  is not almost effective on the orbit  $G^q.q$ , we cannot conclude neither that  $\mathfrak{g}^q$  is spanned by  $\mathfrak{g}_0, \dots, \mathfrak{g}_r$

nor that these subalgebras are in a direct sum (and not even that  $\mathfrak{k}_0$  is trivial or that  $\mathfrak{g}_i$  are ideals).

The main point is that we do not know, in the **non-compact case**, that  $R_{\mathfrak{p}_i, \mathfrak{p}_j} = 0$ , for  $i \neq j$ , (only we know it is true for the restriction to the totally geodesic submanifold  $G^q.q$ ).

### Corollary

*If  $M$  is compact then  $\mathfrak{k}_0 = 0$ ,  $[\mathfrak{g}_i, \mathfrak{g}_j] = 0$ , if  $i \neq j$  and so  $\mathfrak{g}^q$  is the direct sum of the ideals  $\mathfrak{g}_1, \dots, \mathfrak{g}_s$ . Then*

$$G^q = G_0^q \times \dots \times G_r^q \quad (\text{almost direct product})$$

*where  $\text{Lie}(G_i^q) = \mathfrak{g}_i$ .*

But, if the action of  $G^q$  is not almost effective on the orbit  $G^q.q$ , we cannot conclude neither that  $\mathfrak{g}^q$  is spanned by  $\mathfrak{g}_0, \dots, \mathfrak{g}_r$

nor that these subalgebras are in a direct sum (and not even that  $\mathfrak{k}_0$  is trivial or that  $\mathfrak{g}_i$  are ideals).

The main point is that we do not know, in the **non-compact case**, that  $R_{\mathfrak{p}_i, \mathfrak{p}_j} = 0$ , for  $i \neq j$ , (only we know it is true for the restriction to the totally geodesic submanifold  $G^q.q$ ).

### Corollary

*If  $M$  is compact then  $\mathfrak{k}_0 = 0$ ,  $[\mathfrak{g}_i, \mathfrak{g}_j] = 0$ , if  $i \neq j$  and so  $\mathfrak{g}^q$  is the direct sum of the ideals  $\mathfrak{g}_1, \dots, \mathfrak{g}_s$ . Then*

$$G^q = G_0^q \times \dots \times G_r^q \quad (\text{almost direct product})$$

*where  $\text{Lie}(G_i^q) = \mathfrak{g}_i$ .*

But, if the action of  $G^q$  is not almost effective on the orbit  $G^q.q$ , we cannot conclude neither that  $\mathfrak{g}^q$  is spanned by  $\mathfrak{g}_0, \dots, \mathfrak{g}_r$

nor that these subalgebras are in a direct sum (and not even that  $\mathfrak{k}_0$  is trivial or that  $\mathfrak{g}_i$  are ideals).

The main point is that we do not know, in the **non-compact case**, that  $R_{\mathfrak{p}_i, \mathfrak{p}_j} = 0$ , for  $i \neq j$ , (only we know it is true for the restriction to the totally geodesic submanifold  $G^q.q$ ).

### Corollary

*If  $M$  is compact then  $\mathfrak{k}_0 = 0$ ,  $[\mathfrak{g}_i, \mathfrak{g}_j] = 0$ , if  $i \neq j$  and so  $\mathfrak{g}^q$  is the direct sum of the ideals  $\mathfrak{g}_1, \dots, \mathfrak{g}_s$ . Then*

$$G^q = G_0^q \times \dots \times G_r^q \quad (\text{almost direct product})$$

*where  $\text{Lie}(G_i^q) = \mathfrak{g}_i$ .*

But, if the action of  $G^q$  is not almost effective on the orbit  $G^q.q$ , we cannot conclude neither that  $\mathfrak{g}^q$  is spanned by  $\mathfrak{g}_0, \dots, \mathfrak{g}_r$

nor that these subalgebras are in a direct sum (and not even that  $\mathfrak{k}_0$  is trivial or that  $\mathfrak{g}_i$  are ideals).

The main point is that we do not know, in the **non-compact case**, that  $R_{\mathfrak{p}_i, \mathfrak{p}_j} = 0$ , for  $i \neq j$ , (only we know it is true for the restriction to the totally geodesic submanifold  $G^q.q$ ).

## Corollary

*If  $M$  is compact then  $\mathfrak{k}_0 = 0$ ,  $[\mathfrak{g}_i, \mathfrak{g}_j] = 0$ , if  $i \neq j$  and so  $\mathfrak{g}^q$  is the direct sum of the ideals  $\mathfrak{g}_1, \dots, \mathfrak{g}_s$ . Then*

$$G^q = G_0^q \times \dots \times G_r^q \quad (\text{almost direct product})$$

*where  $\text{Lie}(G_i^q) = \mathfrak{g}_i$ .*

But, if the action of  $G^q$  is not almost effective on the orbit  $G^q.q$ , we cannot conclude neither that  $\mathfrak{g}^q$  is spanned by  $\mathfrak{g}_0, \dots, \mathfrak{g}_r$

nor that these subalgebras are in a direct sum (and not even that  $\mathfrak{k}_0$  is trivial or that  $\mathfrak{g}_i$  are ideals).

The main point is that we do not know, in the **non-compact case**, that  $R_{\mathfrak{p}_i, \mathfrak{p}_j} = 0$ , for  $i \neq j$ , (only we know it is true for the restriction to the totally geodesic submanifold  $G^q.q$ ).

## Corollary

*If  $M$  is compact then  $\mathfrak{k}_0 = 0$ ,  $[\mathfrak{g}_i, \mathfrak{g}_j] = 0$ , if  $i \neq j$  and so  $\mathfrak{g}^q$  is the direct sum of the ideals  $\mathfrak{g}_1, \dots, \mathfrak{g}_s$ . Then*

$$G^q = G_0^q \times \dots \times G_r^q \quad (\text{almost direct product})$$

*where  $\text{Lie}(G_i^q) = \mathfrak{g}_i$ .*

But, if the action of  $G^q$  is not almost effective on the orbit  $G^q.q$ , we cannot conclude neither that  $\mathfrak{g}^q$  is spanned by  $\mathfrak{g}_0, \dots, \mathfrak{g}_r$

nor that these subalgebras are in a direct sum (and not even that  $\mathfrak{k}_0$  is trivial or that  $\mathfrak{g}_i$  are ideals).

The main point is that we do not know, in the **non-compact case**, that  $R_{\mathfrak{p}_i, \mathfrak{p}_j} = 0$ , for  $i \neq j$ , (only we know it is true for the restriction to the totally geodesic submanifold  $G^q.q$ ).

## Corollary

If  $M$  is compact then  $\mathfrak{k}_0 = 0$ ,  $[\mathfrak{g}_i, \mathfrak{g}_j] = 0$ , if  $i \neq j$  and so  $\mathfrak{g}^q$  is the direct sum of the ideals  $\mathfrak{g}_1, \dots, \mathfrak{g}_s$ . Then

$$G^q = G_0^q \times \dots \times G_r^q \quad (\text{almost direct product})$$

where  $\text{Lie}(G_i^q) = \mathfrak{g}_i$ .

But, if the action of  $G^q$  is not almost effective on the orbit  $G^q.q$ , we cannot conclude neither that  $\mathfrak{g}^q$  is spanned by  $\mathfrak{g}_0, \dots, \mathfrak{g}_r$

nor that these subalgebras are in a direct sum (and not even that  $\mathfrak{k}_0$  is trivial or that  $\mathfrak{g}_i$  are ideals).

The main point is that we do not know, in the **non-compact case**, that  $R_{\mathfrak{p}_i, \mathfrak{p}_j} = 0$ , for  $i \neq j$ , (only we know it is true for the restriction to the totally geodesic submanifold  $G^q.q$ ).

## Corollary

*If  $M$  is compact then  $\mathfrak{k}_0 = 0$ ,  $[\mathfrak{g}_i, \mathfrak{g}_j] = 0$ , if  $i \neq j$  and so  $\mathfrak{g}^q$  is the direct sum of the ideals  $\mathfrak{g}_1, \dots, \mathfrak{g}_s$ . Then*

$$G^q = G_0^q \times \dots \times G_r^q \quad (\text{almost direct product})$$

*where  $\text{Lie}(G_i^q) = \mathfrak{g}_i$ .*



But, if the action of  $G^q$  is not almost effective on the orbit  $G^q.q$ , we cannot conclude neither that  $\mathfrak{g}^q$  is spanned by  $\mathfrak{g}_0, \dots, \mathfrak{g}_r$

nor that these subalgebras are in a direct sum (and not even that  $\mathfrak{k}_0$  is trivial or that  $\mathfrak{g}_i$  are ideals).

The main point is that we do not know, in the **non-compact case**, that  $R_{\mathfrak{p}_i, \mathfrak{p}_j} = 0$ , for  $i \neq j$ , (only we know it is true for the restriction to the totally geodesic submanifold  $G^q.q$ ).

## Corollary

If  $M$  is compact then  $\mathfrak{k}_0 = 0$ ,  $[\mathfrak{g}_i, \mathfrak{g}_j] = 0$ , if  $i \neq j$  and so  $\mathfrak{g}^q$  is the direct sum of the ideals  $\mathfrak{g}_1, \dots, \mathfrak{g}_s$ . Then

$$G^q = G_0^q \times \dots \times G_r^q \quad (\text{almost direct product})$$

where  $\text{Lie}(G_i^q) = \mathfrak{g}_i$ .

If  $M^n$  is compact then, if  $i \geq 1$ ,  $G_i^q$  is a compact Lie subgroup of  $I(M)$ .

*Facts: assume that  $M^n$  compact.*

*(a)  $G_i^q$  is a compact Lie subgroup of  $I(M)$ , if  $i \geq 1$ .*

*(b) If  $R_{u,v}|_{\mathfrak{s}_q} = 0$ , then  $R_{u,v} = 0$ , for any  $u, v \in \mathfrak{s}_q$ .*

If  $M^n$  is compact then, if  $i \geq 1$ ,  $G_i^q$  is a compact Lie subgroup of  $I(M)$ .

**Facts:** *assume that  $M^n$  compact.*

(a)  $G_i^q$  is a compact Lie subgroup of  $I(M)$ , if  $i \geq 1$ .

(b) If  $R_{u,v}|_{\mathfrak{s}_q} = 0$ , then  $R_{u,v} = 0$ , for any  $u, v \in \mathfrak{s}_q$ .

If  $M^n$  is compact then, if  $i \geq 1$ ,  $G_i^q$  is a compact Lie subgroup of  $I(M)$ .

**Facts:** *assume that  $M^n$  compact.*

- (a)  $G_i^q$  is a compact Lie subgroup of  $I(M)$ , if  $i \geq 1$ .
- (b) If  $R_{u,v} |_{\mathfrak{s}_q} = 0$ , then  $R_{u,v} = 0$ , for any  $u, v \in \mathfrak{s}_q$ .

## Theorem

*Let  $M^n$  be a simply connected compact locally irreducible homogeneous Riemannian manifold, which is not locally symmetric, and let  $k := n - i_s(M)$  be its co-index of symmetry. Then there is a subgroup of isometries  $G \subset I(M)$ , which acts transitively on  $M$  and such that  $\dim(G) \leq \frac{1}{2}k(k+1)$ . Moreover, if the equality holds, then, up to a cover,  $G = Spin(k+1)$  and  $G$  has non-trivial isotropy, if  $k \geq 3$ .*

## Corollary

*Let  $M^n$ ,  $n \geq 3$ , be a simply connected compact locally irreducible homogeneous Riemannian manifold with co-index of  $k = 2$ . Then  $M = Spin(3) \simeq S^3$  with a left invariant metric that belongs to one of two families  $g_s^1$ ,  $g_t^2$  described in the next*

## Theorem

Let  $M^n$  be a simply connected compact locally irreducible homogeneous Riemannian manifold, which is not locally symmetric, and let  $k := n - i_5(M)$  be its co-index of symmetry. Then there is a subgroup of isometries  $G \subset I(M)$ , which acts transitively on  $M$  and such that  $\dim(G) \leq \frac{1}{2}k(k+1)$ . Moreover, if the equality holds, then, up to a cover,  $G = Spin(k+1)$  and  $G$  has non-trivial isotropy, if  $k \geq 3$ .

## Corollary

Let  $M^n$ ,  $n \geq 3$ , be a simply connected compact locally irreducible homogeneous Riemannian manifold with co-index of  $k = 2$ . Then  $M = Spin(3) \simeq S^3$  with a left invariant metric that belongs to one of two families  $g_s^1$ ,  $g_t^2$  described in the next

## Theorem

*Let  $M^n$  be a simply connected compact locally irreducible homogeneous Riemannian manifold, which is not locally symmetric, and let  $k := n - i_5(M)$  be its co-index of symmetry. Then there is a subgroup of isometries  $G \subset I(M)$ , which acts transitively on  $M$  and such that  $\dim(G) \leq \frac{1}{2}k(k+1)$ . Moreover, if the equality holds, then, up to a cover,  $G = Spin(k+1)$  and  $G$  has non-trivial isotropy, if  $k \geq 3$ .*

## Corollary

*Let  $M^n$ ,  $n \geq 3$ , be a simply connected compact locally irreducible homogeneous Riemannian manifold with co-index of  $k = 2$ . Then  $M = Spin(3) \simeq S^3$  with a left invariant metric that belongs to one of two families  $g_s^1$ ,  $g_t^2$  described in the next*

## Theorem

*Let  $M^n$  be a simply connected compact locally irreducible homogeneous Riemannian manifold, which is not locally symmetric, and let  $k := n - i_5(M)$  be its co-index of symmetry. Then there is a subgroup of isometries  $G \subset I(M)$ , which acts transitively on  $M$  and such that  $\dim(G) \leq \frac{1}{2}k(k+1)$ . Moreover, if the equality holds, then, up to a cover,  $G = Spin(k+1)$  and  $G$  has non-trivial isotropy, if  $k \geq 3$ .*

## Corollary

*Let  $M^n$ ,  $n \geq 3$ , be a simply connected compact locally irreducible homogeneous Riemannian manifold with co-index of  $k = 2$ . Then  $M = Spin(3) \simeq S^3$  with a left invariant metric that belongs to one of two families  $g_s^1$ ,  $g_t^2$  described in the next*



## Theorem

Let  $M^n$  be a simply connected compact locally irreducible homogeneous Riemannian manifold, which is not locally symmetric, and let  $k := n - i_5(M)$  be its co-index of symmetry. Then there is a subgroup of isometries  $G \subset I(M)$ , which acts transitively on  $M$  and such that  $\dim(G) \leq \frac{1}{2}k(k+1)$ . Moreover, if the equality holds, then, up to a cover,  $G = Spin(k+1)$  and  $G$  has non-trivial isotropy, if  $k \geq 3$ .

## Corollary

Let  $M^n$ ,  $n \geq 3$ , be a simply connected compact locally irreducible homogeneous Riemannian manifold with co-index of  $k = 2$ . Then  $M = Spin(3) \simeq S^3$  with a left invariant metric that belongs to one of two families  $g_s^1$ ,  $g_t^2$  described in the next

## Theorem

*Let  $M^n$  be a simply connected compact locally irreducible homogeneous Riemannian manifold, which is not locally symmetric, and let  $k := n - i_5(M)$  be its co-index of symmetry. Then there is a subgroup of isometries  $G \subset I(M)$ , which acts transitively on  $M$  and such that  $\dim(G) \leq \frac{1}{2}k(k+1)$ . Moreover, if the equality holds, then, up to a cover,  $G = Spin(k+1)$  and  $G$  has non-trivial isotropy, if  $k \geq 3$ .*

## Corollary

*Let  $M^n$ ,  $n \geq 3$ , be a simply connected compact locally irreducible homogeneous Riemannian manifold with co-index of  $k = 2$ . Then  $M = Spin(3) \simeq S^3$  with a left invariant metric that belongs to one of two families  $g_s^1$ ,  $g_t^2$  described in the next.*

# Examples.

- Left invariant metrics in  $\text{Spin}(3)$ .

Since  $\text{Ad}(\text{Spin}(3)) = \text{SO}(\mathfrak{so}(3)) \simeq \text{SO}(3)$ , with respect to the bi-invariant metric of curvature 1.

any left invariant metric, modulo isometries and rescaling, is determined by a triple of positive numbers

$$(1, \lambda, \beta)$$

which corresponds to a diagonal endomorphism, with respect to the biinvariant metric, in a given orthonormal basis of  $\mathfrak{so}(3)$ .

# Examples.

## - Left invariant metrics in $\text{Spin}(3)$ .

Since  $\text{Ad}(\text{Spin}(3)) = \text{SO}(\mathfrak{so}(3)) \simeq \text{SO}(3)$ , with respect to the bi-invariant metric of curvature 1.

any left invariant metric, modulo isometries and rescaling, is determined by a triple of positive numbers

$$(1, \lambda, \beta)$$

which corresponds to a diagonal endomorphism, with respect to the biinvariant metric, in a given orthonormal basis of  $\mathfrak{so}(3)$ .

## Examples.

### - Left invariant metrics in $\text{Spin}(3)$ .

Since  $\text{Ad}(\text{Spin}(3)) = \text{SO}(\mathfrak{so}(3)) \simeq \text{SO}(3)$ , with respect to the bi-invariant metric of curvature 1.

any left invariant metric, modulo isometries and rescaling, is determined by a triple of positive numbers

$$(1, \lambda, \beta)$$

which corresponds to a diagonal endomorphism, with respect to the biinvariant metric, in a given orthonormal basis of  $\mathfrak{so}(3)$ .

## Examples.

### - Left invariant metrics in $\text{Spin}(3)$ .

Since  $\text{Ad}(\text{Spin}(3)) = \text{SO}(\mathfrak{so}(3)) \simeq \text{SO}(3)$ , with respect to the bi-invariant metric of curvature 1.

any left invariant metric, modulo isometries and rescaling, is determined by a triple of positive numbers

$$(1, \lambda, \beta)$$

which corresponds to a diagonal endomorphism, with respect to the biinvariant metric, in a given orthonormal basis of  $\mathfrak{so}(3)$ .

## Examples.

### - Left invariant metrics in $\text{Spin}(3)$ .

Since  $\text{Ad}(\text{Spin}(3)) = \text{SO}(\mathfrak{so}(3)) \simeq \text{SO}(3)$ , with respect to the bi-invariant metric of curvature 1.

any left invariant metric, modulo isometries and rescaling, is determined by a triple of positive numbers

$$(1, \lambda, \beta)$$

which corresponds to a diagonal endomorphism, with respect to the biinvariant metric, in a given orthonormal basis of  $\mathfrak{so}(3)$ .

## Examples.

### - Left invariant metrics in $\text{Spin}(3)$ .

Since  $\text{Ad}(\text{Spin}(3)) = \text{SO}(\mathfrak{so}(3)) \simeq \text{SO}(3)$ , with respect to the bi-invariant metric of curvature 1.

any left invariant metric, modulo isometries and rescaling, is determined by a triple of positive numbers

$$(1, \lambda, \beta)$$

which corresponds to a diagonal endomorphism, with respect to the biinvariant metric, in a given orthonormal basis of  $\mathfrak{so}(3)$ .



## Examples.

### - Left invariant metrics in $\text{Spin}(3)$ .

Since  $\text{Ad}(\text{Spin}(3)) = \text{SO}(\mathfrak{so}(3)) \simeq \text{SO}(3)$ , with respect to the bi-invariant metric of curvature 1.

any left invariant metric, modulo isometries and rescaling, is determined by a triple of positive numbers

$$(1, \lambda, \beta)$$

which corresponds to a diagonal endomorphism, with respect to the biinvariant metric, in a given orthonormal basis of  $\mathfrak{so}(3)$ .

## Examples.

### - Left invariant metrics in $\text{Spin}(3)$ .

Since  $\text{Ad}(\text{Spin}(3)) = \text{SO}(\mathfrak{so}(3)) \simeq \text{SO}(3)$ , with respect to the bi-invariant metric of curvature 1.

any left invariant metric, modulo isometries and rescaling, is determined by a triple of positive numbers

$$(1, \lambda, \beta)$$

which corresponds to a diagonal endomorphism, with respect to the biinvariant metric, in a given orthonormal basis of  $\mathfrak{so}(3)$ .

## Examples.

### - Left invariant metrics in $\text{Spin}(3)$ .

Since  $\text{Ad}(\text{Spin}(3)) = \text{SO}(\mathfrak{so}(3)) \simeq \text{SO}(3)$ , with respect to the bi-invariant metric of curvature 1.

any left invariant metric, modulo isometries and rescaling, is determined by a triple of positive numbers

$$(1, \lambda, \beta)$$

which corresponds to a diagonal endomorphism, with respect to the biinvariant metric, in a given orthonormal basis of  $\mathfrak{so}(3)$ .

## Examples.

### - Left invariant metrics in $\text{Spin}(3)$ .

Since  $\text{Ad}(\text{Spin}(3)) = \text{SO}(\mathfrak{so}(3)) \simeq \text{SO}(3)$ , with respect to the bi-invariant metric of curvature 1.

any left invariant metric, modulo isometries and rescaling, is determined by a triple of positive numbers

$$(1, \lambda, \beta)$$

which corresponds to a diagonal endomorphism, with respect to the biinvariant metric, in a given orthonormal basis of  $\mathfrak{so}(3)$ .

The metrics with co-index of symmetry 2 are given exactly by the two families of metrics  $g_s^1$  and  $g_t^2$  associated to the triples

$$(1, s, 1 - s), \quad 0 < s < \frac{1}{2}$$

and

$$(1, t, t), \quad 0 < t \neq \frac{1}{2}$$

The isometry group for the first family is  $\text{Spin}(3)$  and for the second family is  $\text{Spin}(3) \times S^1$  (and the tranvections do not lie in  $\text{Spin}(3)$ ), if  $t \neq \frac{1}{2}$ .

Observe that  $(\text{Spin}(3), g_t^2)$  is a Berger sphere. Or equivalently, up to a cover, it is the unit tangent bundle over the 2-sphere of constant curvature different from 1 (in which case the metric would be bi-invariant and the space symmetric).

The metrics with co-index of symmetry 2 are given exactly by the two families of metrics  $g_s^1$  and  $g_t^2$  associated to the triples

$$(1, s, 1 - s), \quad 0 < s < \frac{1}{2}$$

and

$$(1, t, t), \quad 0 < t \neq \frac{1}{2}$$

The isometry group for the first family is  $\text{Spin}(3)$  and for the second family is  $\text{Spin}(3) \times S^1$  (and the tranvections do not lie in  $\text{Spin}(3)$ ), if  $t \neq \frac{1}{2}$ .

Observe that  $(\text{Spin}(3), g_t^2)$  is a Berger sphere. Or equivalently, up to a cover, it is the unit tangent bundle over the 2-sphere of constant curvature different from 1 (in which case the metric would be bi-invariant and the space symmetric).

The metrics with co-index of symmetry 2 are given exactly by the two families of metrics  $g_s^1$  and  $g_t^2$  associated to the triples

$$(1, s, 1 - s), \quad 0 < s < \frac{1}{2}$$

and

$$(1, t, t), \quad 0 < t \neq \frac{1}{2}$$

The isometry group for the first family is  $\text{Spin}(3)$  and for the second family is  $\text{Spin}(3) \times S^1$  (and the tranvections do not lie in  $\text{Spin}(3)$ ), if  $t \neq \frac{1}{2}$ .

Observe that  $(\text{Spin}(3), g_t^2)$  is a Berger sphere. Or equivalently, up to a cover, it is the unit tangent bundle over the 2-sphere of constant curvature different from 1 (in which case the metric would be bi-invariant and the space symmetric).

The metrics with co-index of symmetry 2 are given exactly by the two families of metrics  $g_s^1$  and  $g_t^2$  associated to the triples

$$(1, s, 1 - s), \quad 0 < s < \frac{1}{2}$$

and

$$(1, t, t), \quad 0 < t \neq \frac{1}{2}$$

The isometry group for the first family is  $\text{Spin}(3)$  and for the second family is  $\text{Spin}(3) \times S^1$  (and the tranvections do not lie in  $\text{Spin}(3)$ ), if  $t \neq \frac{1}{2}$ .

Observe that  $(\text{Spin}(3), g_t^2)$  is a Berger sphere. Or equivalently, up to a cover, it is the unit tangent bundle over the 2-sphere of constant curvature different from 1 (in which case the metric would be bi-invariant and the space symmetric).



The metrics with co-index of symmetry 2 are given exactly by the two families of metrics  $g_s^1$  and  $g_t^2$  associated to the triples

$$(1, s, 1 - s), \quad 0 < s < \frac{1}{2}$$

and

$$(1, t, t), \quad 0 < t \neq 1$$

The isometry group for the first family is  $\text{Spin}(3)$  and for the second family is  $\text{Spin}(3) \times S^1$  (and the tranvections do not lie in  $\text{Spin}(3)$ ), if  $t \neq \frac{1}{2}$ .

Observe that  $(\text{Spin}(3), g_t^2)$  is a Berger sphere. Or equivalently, up to a cover, it is the unit tangent bundle over the 2-sphere of constant curvature different from 1 (in which case the metric would be bi-invariant and the space symmetric).

The metrics with co-index of symmetry 2 are given exactly by the two families of metrics  $g_s^1$  and  $g_t^2$  associated to the triples

$$(1, s, 1 - s), \quad 0 < s < \frac{1}{2}$$

and

$$(1, t, t), \quad 0 < t \neq \frac{1}{2}$$

The isometry group for the first family is  $\text{Spin}(3)$  and for the second family is  $\text{Spin}(3) \times S^1$  (and the tranvections do not lie in  $\text{Spin}(3)$ ), if  $t \neq \frac{1}{2}$ .

Observe that  $(\text{Spin}(3), g_t^2)$  is a Berger sphere. Or equivalently, up to a cover, it is the unit tangent bundle over the 2-sphere of constant curvature different from 1 (in which case the metric would be bi-invariant and the space symmetric).

The metrics with co-index of symmetry 2 are given exactly by the two families of metrics  $g_s^1$  and  $g_t^2$  associated to the triples

$$(1, s, 1 - s), \quad 0 < s < \frac{1}{2}$$

and

$$(1, t, t), \quad 0 < t \neq 1$$

The isometry group for the first family is  $\text{Spin}(3)$  and for the second family is  $\text{Spin}(3) \times S^1$  (and the tranvections do not lie in  $\text{Spin}(3)$ ), if  $t \neq \frac{1}{2}$ .

Observe that  $(\text{Spin}(3), g_t^2)$  is a Berger sphere. Or equivalently, up to a cover, it is the unit tangent bundle over the 2-sphere of constant curvature different from 1 (in which case the metric would be bi-invariant and the space symmetric).

The metrics with co-index of symmetry 2 are given exactly by the two families of metrics  $g_s^1$  and  $g_t^2$  associated to the triples

$$(1, s, 1 - s), \quad 0 < s < \frac{1}{2}$$

and

$$(1, t, t), \quad 0 < t \neq \frac{1}{2}$$

The isometry group for the first family is  $\text{Spin}(3)$  and for the second family is  $\text{Spin}(3) \times S^1$  (and the tranvections do not lie in  $\text{Spin}(3)$ ), if  $t \neq \frac{1}{2}$ .

Observe that  $(\text{Spin}(3), g_t^2)$  is a Berger sphere. Or equivalently, up to a cover, it is the unit tangent bundle over the 2-sphere of constant curvature different from 1 (in which case the metric would be bi-invariant and the space symmetric).

The metrics with co-index of symmetry 2 are given exactly by the two families of metrics  $g_s^1$  and  $g_t^2$  associated to the triples

$$(1, s, 1 - s), \quad 0 < s < \frac{1}{2}$$

and

$$(1, t, t), \quad 0 < t \neq \frac{1}{2}$$

The isometry group for the first family is  $\text{Spin}(3)$  and for the second family is  $\text{Spin}(3) \times S^1$  (and the tranvections do not lie in  $\text{Spin}(3)$ ), if  $t \neq \frac{1}{2}$ .

Observe that  $(\text{Spin}(3), g_t^2)$  is a Berger sphere. Or equivalently, up to a cover, it is the unit tangent bundle over the 2-sphere of constant curvature different from 1 (in which case the metric would be bi-invariant and the space symmetric).

The metrics with co-index of symmetry 2 are given exactly by the two families of metrics  $g_s^1$  and  $g_t^2$  associated to the triples

$$(1, s, 1 - s), \quad 0 < s < \frac{1}{2}$$

and

$$(1, t, t), \quad 0 < t \neq \frac{1}{2}$$

The isometry group for the first family is  $\text{Spin}(3)$  and for the second family is  $\text{Spin}(3) \times S^1$  (and the tranvections do not lie in  $\text{Spin}(3)$ ), if  $t \neq \frac{1}{2}$ .

Observe that  $(\text{Spin}(3), g_t^2)$  is a Berger sphere. Or equivalently, up to a cover, it is the unit tangent bundle over the 2-sphere of constant curvature different from 1 (in which case the metric would be bi-invariant and the space symmetric).

The metrics with co-index of symmetry 2 are given exactly by the two families of metrics  $g_s^1$  and  $g_t^2$  associated to the triples

$$(1, s, 1 - s), \quad 0 < s < \frac{1}{2}$$

and

$$(1, t, t), \quad 0 < t \neq \frac{1}{2}$$

The isometry group for the first family is  $\text{Spin}(3)$  and for the second family is  $\text{Spin}(3) \times S^1$  (and the tranvections do not lie in  $\text{Spin}(3)$ ), if  $t \neq \frac{1}{2}$ .

Observe that  $(\text{Spin}(3), g_t^2)$  is a Berger sphere. Or equivalently, up to a cover, it is the unit tangent bundle over the 2-sphere of constant curvature different from 1 (in which case the metric would be bi-invariant and the space symmetric).

The metrics with co-index of symmetry 2 are given exactly by the two families of metrics  $g_s^1$  and  $g_t^2$  associated to the triples

$$(1, s, 1 - s), \quad 0 < s < \frac{1}{2}$$

and

$$(1, t, t), \quad 0 < t \neq \frac{1}{2}$$

The isometry group for the first family is  $\text{Spin}(3)$  and for the second family is  $\text{Spin}(3) \times S^1$  (and the tranvections do not lie in  $\text{Spin}(3)$ ), if  $t \neq \frac{1}{2}$ .

Observe that  $(\text{Spin}(3), g_t^2)$  is a Berger sphere. Or equivalently, up to a cover, it is the unit tangent bundle over the 2-sphere of constant curvature different from 1 (in which case the metric would be bi-invariant and the space symmetric).



## - The unit tangent bundle over the sphere of curvature 2.

*The distribution of symmetry  $\mathfrak{s}$ , of the unit tangent bundle  $M^{2n-1}$  of the sphere  $S_2^n$  of curvature 2, coincides with the vertical distribution  $\nu$ . In particular,  $i_{\mathfrak{s}} = n - 1$ , where  $i_{\mathfrak{s}} = \dim(\mathfrak{s})$  is the index of symmetry (or equivalently, the co-index of symmetry is equals to  $n$ ).*

## - The unit tangent bundle over the sphere of curvature 2.

*The distribution of symmetry  $\mathfrak{s}$ , of the unit tangent bundle  $M^{2n-1}$  of the sphere  $S_2^n$  of curvature 2, coincides with the vertical distribution  $\nu$ . In particular,  $i_{\mathfrak{s}} = n - 1$ , where  $i_{\mathfrak{s}} = \dim(\mathfrak{s})$  is the index of symmetry (or equivalently, the co-index of symmetry is equals to  $n$ ).*

## - The unit tangent bundle over the sphere of curvature 2.

*The distribution of symmetry  $\mathfrak{s}$ , of the unit tangent bundle  $M^{2n-1}$  of the sphere  $S_2^n$  of curvature 2, coincides with the vertical distribution  $\nu$ . In particular,  $i_{\mathfrak{s}} = n - 1$ , where  $i_{\mathfrak{s}} = \dim(\mathfrak{s})$  is the index of symmetry (or equivalently, the co-index of symmetry is equals to  $n$ ).*

## - The unit tangent bundle over the sphere of curvature 2.

*The distribution of symmetry  $\mathfrak{s}$ , of the unit tangent bundle  $M^{2n-1}$  of the sphere  $S_2^n$  of curvature 2, coincides with the vertical distribution  $\nu$ . In particular,  $i_{\mathfrak{s}} = n - 1$ , where  $i_{\mathfrak{s}} = \dim(\mathfrak{s})$  is the index of symmetry (or equivalently, the co-index of symmetry is equals to  $n$ ).*

## - The unit tangent bundle over the sphere of curvature 2.

*The distribution of symmetry  $\mathfrak{s}$ , of the unit tangent bundle  $M^{2n-1}$  of the sphere  $S_2^n$  of curvature 2, coincides with the vertical distribution  $\nu$ . In particular,  $i_{\mathfrak{s}} = n - 1$ , where  $i_{\mathfrak{s}} = \dim(\mathfrak{s})$  is the index of symmetry (or equivalently, the co-index of symmetry is equals to  $n$ ).*

## - The unit tangent bundle over the sphere of curvature 2.

*The distribution of symmetry  $\mathfrak{s}$ , of the unit tangent bundle  $M^{2n-1}$  of the sphere  $S_2^n$  of curvature 2, coincides with the vertical distribution  $\nu$ . In particular,  $i_{\mathfrak{s}} = n - 1$ , where  $i_{\mathfrak{s}} = \dim(\mathfrak{s})$  is the index of symmetry (or equivalently, the co-index of symmetry is equals to  $n$ ).*

## - The unit tangent bundle over the sphere of curvature 2.

*The distribution of symmetry  $\mathfrak{s}$ , of the unit tangent bundle  $M^{2n-1}$  of the sphere  $S_2^n$  of curvature 2, coincides with the vertical distribution  $\nu$ . In particular,  $i_{\mathfrak{s}} = n - 1$ , where  $i_{\mathfrak{s}} = \dim(\mathfrak{s})$  is the index of symmetry (or equivalently, the co-index of symmetry is equals to  $n$ ).*

## - Naturally reductive spaces whose isotropy has fixed vectors

Let  $M = G/H$  be a homogeneous compact Riemannian manifold with a  $G$ -invariant metric  $\langle \cdot, \cdot \rangle$ .

The space  $M$  is said to be *naturally reductive* if there exists a reductive decomposition

$$\mathfrak{g} = \mathfrak{h} \oplus \mathfrak{m},$$

where  $\mathfrak{g} = \text{Lie}(G)$ ,  $\mathfrak{h} = \text{Lie}(H)$ ,  $\text{Ad}(H)\mathfrak{m} \subset \mathfrak{m}$ , such that the geodesics by  $\rho = [e]$  are given by

$$\gamma_{X,\rho} = \text{Exp}(tX) \cdot \rho$$

for all  $X \in \mathfrak{m}$ . In other words, the Riemannian geodesics coincide with the  $\nabla^c$ -geodesics, where  $\nabla^c$  is the canonical connection, which is a metric connection, of  $M$  associated to the reductive decomposition. This is in fact equivalent to the property that  $[X, \cdot]_{\mathfrak{m}} : \mathfrak{m} \rightarrow \mathfrak{m}$  is skew-symmetric, for all  $X \in \mathfrak{m}$  ( $\mathfrak{m} \simeq T_{\rho}M$ ).



## - Naturally reductive spaces whose isotropy has fixed vectors

Let  $M = G/H$  be a homogeneous compact Riemannian manifold with a  $G$ -invariant metric  $\langle \cdot, \cdot \rangle$ .

The space  $M$  is said to be *naturally reductive* if there exists a reductive decomposition

$$\mathcal{G} = \mathfrak{h} \oplus \mathfrak{m},$$

where  $\mathcal{G} = \text{Lie}(G)$ ,  $\mathfrak{h} = \text{Lie}(H)$ ,  $\text{Ad}(H)\mathfrak{m} \subset \mathfrak{m}$ , such that the geodesics by  $\rho = [e]$  are given by

$$\gamma_{X,\rho} = \text{Exp}(tX) \cdot \rho$$

for all  $X \in \mathfrak{m}$ . In other words, the Riemannian geodesics coincide with the  $\nabla^c$ -geodesics, where  $\nabla^c$  is the canonical connection, which is a metric connection, of  $M$  associated to the reductive decomposition. This is in fact equivalent to the property that  $[X, \cdot]_{\mathfrak{m}} : \mathfrak{m} \rightarrow \mathfrak{m}$  is skew-symmetric, for all  $X \in \mathfrak{m}$  ( $\mathfrak{m} \simeq T_{\rho}M$ ).

## - Naturally reductive spaces whose isotropy has fixed vectors

Let  $M = G/H$  be a homogeneous compact Riemannian manifold with a  $G$ -invariant metric  $\langle \cdot, \cdot \rangle$ .

The space  $M$  is said to be *naturally reductive* if there exists a reductive decomposition

$$\mathcal{G} = \mathfrak{h} \oplus \mathfrak{m},$$

where  $\mathcal{G} = \text{Lie}(G)$ ,  $\mathfrak{h} = \text{Lie}(H)$ ,  $\text{Ad}(H)\mathfrak{m} \subset \mathfrak{m}$ , such that the geodesics by  $\rho = [e]$  are given by

$$\gamma_{X.\rho} = \text{Exp}(tX).\rho$$

for all  $X \in \mathfrak{m}$ . In other words, the Riemannian geodesics coincide with the  $\nabla^c$ -geodesics, where  $\nabla^c$  is the canonical connection, which is a metric connection, of  $M$  associated to the reductive decomposition. This is in fact equivalent to the property that  $[X, \cdot]_{\mathfrak{m}} : \mathfrak{m} \rightarrow \mathfrak{m}$  is skew-symmetric, for all  $X \in \mathfrak{m}$  ( $\mathfrak{m} \simeq T_{\rho}M$ ).

## - Naturally reductive spaces whose isotropy has fixed vectors

Let  $M = G/H$  be a homogeneous compact Riemannian manifold with a  $G$ -invariant metric  $\langle \cdot, \cdot \rangle$ .

The space  $M$  is said to be *naturally reductive* if there exists a reductive decomposition

$$\mathcal{G} = \mathfrak{h} \oplus \mathfrak{m},$$

where  $\mathcal{G} = \text{Lie}(G)$ ,  $\mathfrak{h} = \text{Lie}(H)$ ,  $\text{Ad}(H)\mathfrak{m} \subset \mathfrak{m}$ , such that the geodesics by  $\rho = [e]$  are given by

$$\gamma_{X.\rho} = \text{Exp}(tX).\rho$$

for all  $X \in \mathfrak{m}$ . In other words, the Riemannian geodesics coincide with the  $\nabla^c$ -geodesics, where  $\nabla^c$  is the canonical connection, which is a metric connection, of  $M$  associated to the reductive decomposition. This is in fact equivalent to the property that  $[X, \cdot]_{\mathfrak{m}} : \mathfrak{m} \rightarrow \mathfrak{m}$  is skew-symmetric, for all  $X \in \mathfrak{m}$  ( $\mathfrak{m} \simeq T_{\rho}M$ ).

## - Naturally reductive spaces whose isotropy has fixed vectors

Let  $M = G/H$  be a homogeneous compact Riemannian manifold with a  $G$ -invariant metric  $\langle \cdot, \cdot \rangle$ .

The space  $M$  is said to be *naturally reductive* if there exists a reductive decomposition

$$\mathcal{G} = \mathfrak{h} \oplus \mathfrak{m},$$

where  $\mathcal{G} = \text{Lie}(G)$ ,  $\mathfrak{h} = \text{Lie}(H)$ ,  $\text{Ad}(H)\mathfrak{m} \subset \mathfrak{m}$ , such that the geodesics by  $\rho = [e]$  are given by

$$\gamma_{X.\rho} = \text{Exp}(tX).\rho$$

for all  $X \in \mathfrak{m}$ . In other words, the Riemannian geodesics coincide with the  $\nabla^c$ -geodesics, where  $\nabla^c$  is the canonical connection, which is a metric connection, of  $M$  associated to the reductive decomposition. This is in fact equivalent to the property that  $[X, \cdot]_{\mathfrak{m}} : \mathfrak{m} \rightarrow \mathfrak{m}$  is skew-symmetric, for all  $X \in \mathfrak{m}$  ( $\mathfrak{m} \simeq T_{\rho}M$ ).

## - Naturally reductive spaces whose isotropy has fixed vectors

Let  $M = G/H$  be a homogeneous compact Riemannian manifold with a  $G$ -invariant metric  $\langle \cdot, \cdot \rangle$ .

The space  $M$  is said to be *naturally reductive* if there exists a reductive decomposition

$$\mathcal{G} = \mathfrak{h} \oplus \mathfrak{m},$$

where  $\mathcal{G} = \text{Lie}(G)$ ,  $\mathfrak{h} = \text{Lie}(H)$ ,  $\text{Ad}(H)\mathfrak{m} \subset \mathfrak{m}$ , such that the geodesics by  $p = [e]$  are given by

$$\gamma_{X.p} = \text{Exp}(tX).p$$

for all  $X \in \mathfrak{m}$ . In other words, the Riemannian geodesics coincide with the  $\nabla^c$ -geodesics, where  $\nabla^c$  is the canonical connection, which is a metric connection, of  $M$  associated to the reductive decomposition. This is in fact equivalent to the property that  $[X, \cdot]_{\mathfrak{m}} : \mathfrak{m} \rightarrow \mathfrak{m}$  is skew-symmetric, for all  $X \in \mathfrak{m}$  ( $\mathfrak{m} \simeq T_p M$ ).

The Levi-Civita connection is given by

$$\nabla_v \tilde{W} = \frac{1}{2}[\tilde{v}, \tilde{W}]_p,$$

and

$$\nabla_v^c \tilde{W} = [\tilde{v}, \tilde{W}]_p,$$

where, for  $u \in T_p M$ ,  $\tilde{u}$  is the Killing field on  $M$  induced by the unique  $X \in \mathfrak{m}$  such that  $X.p = u$  (i.e.  $\tilde{u}(q) = X.q$ ).

The Levi-Civita connection is given by

$$\nabla_v \tilde{W} = \frac{1}{2}[\tilde{v}, \tilde{W}]_p,$$

and

$$\nabla_v^c \tilde{W} = [\tilde{v}, \tilde{W}]_p,$$

where, for  $u \in T_p M$ ,  $\tilde{u}$  is the Killing field on  $M$  induced by the unique  $X \in \mathfrak{m}$  such that  $X.p = u$  (i.e.  $\tilde{u}(q) = X.q$ ).

The Levi-Civita connection is given by

$$\nabla_v \tilde{w} = \frac{1}{2}[\tilde{v}, \tilde{w}]_p,$$

and

$$\nabla_v^c \tilde{w} = [\tilde{v}, \tilde{w}]_p,$$

where, for  $u \in T_p M$ ,  $\tilde{u}$  is the Killing field on  $M$  induced by the unique  $X \in \mathfrak{m}$  such that  $X.p = u$  (i.e.  $\tilde{u}(q) = X.q$ ).



The Levi-Civita connection is given by

$$\nabla_v \tilde{w} = \frac{1}{2}[\tilde{v}, \tilde{w}]_p,$$

and

$$\nabla_v^c \tilde{w} = [\tilde{v}, \tilde{w}]_p,$$

where, for  $u \in T_p M$ ,  $\tilde{u}$  is the Killing field on  $M$  induced by the unique  $X \in \mathfrak{m}$  such that  $X.p = u$  (i.e.  $\tilde{u}(q) = X.q$ ).

The Levi-Civita connection is given by

$$\nabla_v \tilde{w} = \frac{1}{2}[\tilde{v}, \tilde{w}]_p,$$

and

$$\nabla_v^c \tilde{w} = [\tilde{v}, \tilde{w}]_p,$$

where, for  $u \in T_p M$ ,  $\tilde{u}$  is the Killing field on  $M$  induced by the unique  $X \in \mathfrak{m}$  such that  $X.p = u$  (i.e.  $\tilde{u}(q) = X.q$ ).

The Levi-Civita connection is given by

$$\nabla_v \tilde{w} = \frac{1}{2}[\tilde{v}, \tilde{w}]_p,$$

and

$$\nabla_v^c \tilde{w} = [\tilde{v}, \tilde{w}]_p,$$

where, for  $u \in T_p M$ ,  $\tilde{u}$  is the Killing field on  $M$  induced by the unique  $X \in \mathfrak{m}$  such that  $X.p = u$  (i.e.  $\tilde{u}(q) = X.q$ ).

The Levi-Civita connection is given by

$$\nabla_v \tilde{w} = \frac{1}{2}[\tilde{v}, \tilde{w}]_p,$$

and

$$\nabla_v^c \tilde{w} = [\tilde{v}, \tilde{w}]_p,$$

where, for  $u \in T_p M$ ,  $\tilde{u}$  is the Killing field on  $M$  induced by the unique  $X \in \mathfrak{m}$  such that  $X.p = u$  (i.e.  $\tilde{u}(q) = X.q$ ).

The difference tensor between both connections is given by

$$D_\nu w = \nabla_\nu \tilde{w} - \nabla_\nu^c \tilde{w} = -\frac{1}{2}[\tilde{\nu}, \tilde{w}]_p = -\nabla_\nu \tilde{w}.$$

The tensor  $D$  is totally skew, i.e.  $\langle D_\nu w, z \rangle$  is a 3-form.

Let  $M$  be a compact locally irreducible (non-symmetric) naturally reductive space. Let now, keeping the previous notation,

$$\mathfrak{m}_0 \subset \mathfrak{m} \simeq T_p M$$

be the set of fixed vectors of the isotropy at  $q$ .

The difference tensor between both connections is given by

$$D_\nu w = \nabla_\nu \tilde{w} - \nabla_\nu^c \tilde{w} = -\frac{1}{2}[\tilde{v}, \tilde{w}]_\rho = -\nabla_\nu \tilde{w}.$$

The tensor  $D$  is totally skew, i.e.  $\langle D_\nu w, z \rangle$  is a 3-form.

Let  $M$  be a compact locally irreducible (non-symmetric) naturally reductive space. Let now, keeping the previous notation,

$$\mathfrak{m}_0 \subset \mathfrak{m} \simeq T_\rho M$$

be the set of fixed vectors of the isotropy at  $q$ .

The difference tensor between both connections is given by

$$D_\nu w = \nabla_\nu \tilde{w} - \nabla_\nu^c \tilde{w} = -\frac{1}{2}[\tilde{\nu}, \tilde{w}]_\rho = -\nabla_\nu \tilde{w}.$$

The tensor  $D$  is totally skew, i.e.  $\langle D_\nu w, z \rangle$  is a 3-form.

Let  $M$  be a compact locally irreducible (non-symmetric) naturally reductive space. Let now, keeping the previous notation,

$$\mathfrak{m}_0 \subset \mathfrak{m} \simeq T_\rho M$$

be the set of fixed vectors of the isotropy at  $q$ .

The difference tensor between both connections is given by

$$D_V w = \nabla_V \tilde{w} - \nabla_V^c \tilde{w} = -\frac{1}{2}[\tilde{v}, \tilde{w}]_p = -\nabla_V \tilde{w}.$$

The tensor  $D$  is totally skew, i.e.  $\langle D_V w, z \rangle$  is a 3-form.

Let  $M$  be a compact locally irreducible (non-symmetric) naturally reductive space. Let now, keeping the previous notation,

$$\mathfrak{m}_0 \subset \mathfrak{m} \simeq T_p M$$

be the set of fixed vectors of the isotropy at  $q$ .



The difference tensor between both connections is given by

$$D_\nu w = \nabla_\nu \tilde{w} - \nabla_\nu^c \tilde{w} = -\frac{1}{2}[\tilde{\nu}, \tilde{w}]_p = -\nabla_\nu \tilde{w}.$$

The tensor  $D$  is totally skew, i.e.  $\langle D_\nu w, z \rangle$  is a 3-form.

Let  $M$  be a compact locally irreducible (non-symmetric) naturally reductive space. Let now, keeping the previous notation,

$$\mathfrak{m}_0 \subset \mathfrak{m} \simeq T_p M$$

be the set of fixed vectors of the isotropy at  $q$ .

The difference tensor between both connections is given by

$$D_\nu w = \nabla_\nu \tilde{w} - \nabla_\nu^c \tilde{w} = -\frac{1}{2}[\tilde{\nu}, \tilde{w}]_p = -\nabla_\nu \tilde{w}.$$

The tensor  $D$  is totally skew, i.e.  $\langle D_\nu w, z \rangle$  is a 3-form.

Let  $M$  be a compact locally irreducible (non-symmetric) naturally reductive space. Let now, keeping the previous notation,

$$\mathfrak{m}_0 \subset \mathfrak{m} \simeq T_p M$$

be the set of fixed vectors of the isotropy at  $q$ .

The difference tensor between both connections is given by

$$D_\nu w = \nabla_\nu \tilde{w} - \nabla_\nu^c \tilde{w} = -\frac{1}{2}[\tilde{\nu}, \tilde{w}]_p = -\nabla_\nu \tilde{w}.$$

The tensor  $D$  is totally skew, i.e.  $\langle D_\nu w, z \rangle$  is a 3-form.

Let  $M$  be a compact locally irreducible (non-symmetric) naturally reductive space. Let now, keeping the previous notation,

$$\mathfrak{m}_0 \subset \mathfrak{m} \simeq T_p M$$

be the set of fixed vectors of the isotropy at  $q$ .

Let  $\hat{w}$  denote the  $G$ -invariant vector with  $\hat{w}(q) = w \in \mathfrak{m}_0$ .

Such a field is parallel with respect to the canonical connection. In fact, any  $G$ -invariant tensor is  $\nabla^c$ -parallel.

Then, for any  $v \in \mathfrak{m} \simeq T_p M$ ,  $w \in \mathfrak{m}_0$ ,

$$(\nabla_v \hat{w})_q = D_v w$$

Observe, since  $D$  is totally skew, that  $\hat{w}$  satisfies the Killing equation and hence it is a Killing field.

**Remark.** There are no more new Killing fields in  $M$ , since the canonical connection is unique (unless  $M$  is round sphere, or a Lie group, with a bi-invariant metric). This is by making use of the so-called *skew-torsion holonomy theorem* (O.- Reggiani, Crelle's 2011)

$$\text{Lie}(I(M)) = \mathfrak{g} \oplus \hat{\mathfrak{m}}_0$$

(direct sum of ideals).

Introduction

The index of symmetry

The dimension bound

Examples

Open questions

Let  $\hat{w}$  denote the  $G$ -invariant vector with  $\hat{w}(q) = w \in \mathfrak{m}_0$ .

Such a field is parallel with respect to the canonical connection.

In fact, any  $G$ -invariant tensor is  $\nabla^c$ -parallel.

Then, for any  $v \in \mathfrak{m} \simeq T_p M$ ,  $w \in \mathfrak{m}_0$ ,

$$(\nabla_v \hat{w})_q = D_v w$$

Observe, since  $D$  is totally skew, that  $\hat{w}$  satisfies the Killing equation and hence it is a Killing field.

**Remark.** There are no more new Killing fields in  $M$ , since the canonical connection is unique (unless  $M$  is round sphere, or a Lie group, with a bi-invariant metric). This is by making use of the so-called *skew-torsion holonomy theorem* (O.- Reggiani, Crelle's 2011)

$$\text{Lie}(I(M)) = \mathfrak{g} \oplus \hat{\mathfrak{m}}_0$$

(direct sum of ideals).

Introduction

The index of symmetry

The dimension bound

Examples

Open questions

Let  $\hat{w}$  denote the  $G$ -invariant vector with  $\hat{w}(q) = w \in \mathfrak{m}_0$ .  
**Such a field is parallel with respect to the canonical connection.** In fact, any  $G$ -invariant tensor is  $\nabla^c$ -parallel.

Then, for any  $v \in \mathfrak{m} \simeq T_p M$ ,  $w \in \mathfrak{m}_0$ ,

$$(\nabla_v \hat{w})_q = D_v w$$

Observe, since  $D$  is totally skew, that  $\hat{w}$  satisfies the Killing equation and hence it is a Killing field.

**Remark.** There are no more new Killing fields in  $M$ , since the canonical connection is unique (unless  $M$  is round sphere, or a Lie group, with a bi-invariant metric). This is by making use of the so-called *skew-torsion holonomy theorem* (O.- Reggiani, Crelle's 2011)

$$\text{Lie}(I(M)) = \mathfrak{g} \oplus \hat{\mathfrak{m}}_0$$

(direct sum of ideals).

Let  $\hat{w}$  denote the  $G$ -invariant vector with  $\hat{w}(q) = w \in \mathfrak{m}_0$ .  
**Such a field is parallel with respect to the canonical connection.** In fact, any  $G$ -invariant tensor is  $\nabla^c$ -parallel.  
 Then, for any  $v \in \mathfrak{m} \simeq T_p M$ ,  $w \in \mathfrak{m}_0$ ,

$$(\nabla_v \hat{w})_q = D_v w$$

Observe, since  $D$  is totally skew, that  $\hat{w}$  satisfies the Killing equation and hence it is a Killing field.

**Remark.** There are no more new Killing fields in  $M$ , since the canonical connection is unique (unless  $M$  is round sphere, or a Lie group, with a bi-invariant metric). This is by making use of the so-called *skew-torsion holonomy theorem* (O.- Reggiani, Crelle's 2011)

$$\text{Lie}(I(M)) = \mathfrak{g} \oplus \hat{\mathfrak{m}}_0$$

(direct sum of ideals).

Let  $\hat{w}$  denote the  $G$ -invariant vector with  $\hat{w}(q) = w \in \mathfrak{m}_0$ .  
**Such a field is parallel with respect to the canonical connection.** In fact, any  $G$ -invariant tensor is  $\nabla^c$ -parallel.  
 Then, for any  $v \in \mathfrak{m} \simeq T_p M$ ,  $w \in \mathfrak{m}_0$ ,

$$(\nabla_v \hat{w})_q = D_v w$$

Observe, since  $D$  is totally skew, that  $\hat{w}$  satisfies the Killing equation and hence it is a Killing field.

**Remark.** There are no more new Killing fields in  $M$ , since the canonical connection is unique (unless  $M$  is round sphere, or a Lie group, with a bi-invariant metric). This is by making use of the so-called *skew-torsion holonomy theorem* (O.- Reggiani, Crelle's 2011)

$$\text{Lie}(I(M)) = \mathfrak{g} \oplus \hat{\mathfrak{m}}_0$$

(direct sum of ideals).



Let  $\hat{w}$  denote the  $G$ -invariant vector with  $\hat{w}(q) = w \in \mathfrak{m}_0$ .  
**Such a field is parallel with respect to the canonical connection.** In fact, any  $G$ -invariant tensor is  $\nabla^c$ -parallel.  
 Then, for any  $v \in \mathfrak{m} \simeq T_p M$ ,  $w \in \mathfrak{m}_0$ ,

$$(\nabla_v \hat{w})_q = D_v w$$

Observe, since  $D$  is totally skew, that  $\hat{w}$  satisfies the Killing equation and hence it is a Killing field.

**Remark.** There are no more new Killing fields in  $M$ , since the canonical connection is unique (unless  $M$  is round sphere, or a Lie group, with a bi-invariant metric). This is by making use of the so-called *skew-torsion holonomy theorem* (O.- Reggiani, Crelle's 2011)

$$\text{Lie}(I(M)) = \mathfrak{g} \oplus \hat{\mathfrak{m}}_0$$

(direct sum of ideals).

Let  $\hat{w}$  denote the  $G$ -invariant vector with  $\hat{w}(q) = w \in \mathfrak{m}_0$ . Such a field is parallel with respect to the canonical connection. In fact, any  $G$ -invariant tensor is  $\nabla^c$ -parallel. Then, for any  $v \in \mathfrak{m} \simeq T_p M$ ,  $w \in \mathfrak{m}_0$ ,

$$(\nabla_v \hat{w})_q = D_v w$$

Observe, since  $D$  is totally skew, that  $\hat{w}$  satisfies the Killing equation and hence it is a Killing field.

**Remark.** There are no more new Killing fields in  $M$ , since the canonical connection is unique (unless  $M$  is round sphere, or a Lie group, with a bi-invariant metric). This is by making use of the so-called *skew-torsion holonomy theorem* (O.- Reggiani, Crelle's 2011)

$$\text{Lie}(I(M)) = \mathfrak{g} \oplus \hat{\mathfrak{m}}_0$$

(direct sum of ideals).

Let  $\hat{w}$  denote the  $G$ -invariant vector with  $\hat{w}(q) = w \in \mathfrak{m}_0$ . Such a field is parallel with respect to the canonical connection. In fact, any  $G$ -invariant tensor is  $\nabla^c$ -parallel. Then, for any  $v \in \mathfrak{m} \simeq T_p M$ ,  $w \in \mathfrak{m}_0$ ,

$$(\nabla_v \hat{w})_q = D_v w$$

Observe, since  $D$  is totally skew, that  $\hat{w}$  satisfies the Killing equation and hence it is a Killing field.

**Remark.** There are no more new Killing fields in  $M$ , since the canonical connection is unique (unless  $M$  is round sphere, or a Lie group, with a bi-invariant metric). This is by making use of the so-called *skew-torsion holonomy theorem* (O.- Reggiani, Crelle's 2011)

$$\text{Lie}(I(M)) = \mathfrak{g} \oplus \hat{\mathfrak{m}}_0$$

(direct sum of ideals).

Let  $\hat{w}$  denote the  $G$ -invariant vector with  $\hat{w}(q) = w \in \mathfrak{m}_0$ .  
 Such a field is parallel with respect to the canonical connection. In fact, any  $G$ -invariant tensor is  $\nabla^c$ -parallel.  
 Then, for any  $v \in \mathfrak{m} \simeq T_p M$ ,  $w \in \mathfrak{m}_0$ ,

$$(\nabla_v \hat{w})_q = D_v w$$

Observe, since  $D$  is totally skew, that  $\hat{w}$  satisfies the Killing equation and hence it is a Killing field.

**Remark.** There are no more new Killing fields in  $M$ , since the canonical connection is unique (unless  $M$  is round sphere, or a Lie group, with a bi-invariant metric). This is by making use of the so-called *skew-torsion holonomy theorem* (O.- Reggiani, Crelle's 2011)

$$\text{Lie}(I(M)) = \mathfrak{g} \oplus \hat{\mathfrak{m}}_0$$

(direct sum of ideals).

Let  $\hat{w}$  denote the  $G$ -invariant vector with  $\hat{w}(q) = w \in \mathfrak{m}_0$ .  
 Such a field is parallel with respect to the canonical connection. In fact, any  $G$ -invariant tensor is  $\nabla^c$ -parallel.  
 Then, for any  $v \in \mathfrak{m} \simeq T_p M$ ,  $w \in \mathfrak{m}_0$ ,

$$(\nabla_v \hat{w})_q = D_v w$$

Observe, since  $D$  is totally skew, that  $\hat{w}$  satisfies the Killing equation and hence it is a Killing field.

**Remark.** There are no more new Killing fields in  $M$ , since the canonical connection is unique (unless  $M$  is round sphere, or a Lie group, with a bi-invariant metric). This is by making use of the so-called *skew-torsion holonomy theorem* (O.- Reggiani, Crelle's 2011)

$$\text{Lie}(I(M)) = \mathfrak{g} \oplus \hat{\mathfrak{m}}_0$$

(direct sum of ideals).

Let  $\hat{w}$  denote the  $G$ -invariant vector with  $\hat{w}(q) = w \in \mathfrak{m}_0$ .  
 Such a field is parallel with respect to the canonical connection. In fact, any  $G$ -invariant tensor is  $\nabla^c$ -parallel.  
 Then, for any  $v \in \mathfrak{m} \simeq T_p M$ ,  $w \in \mathfrak{m}_0$ ,

$$(\nabla_v \hat{w})_q = D_v w$$

Observe, since  $D$  is totally skew, that  $\hat{w}$  satisfies the Killing equation and hence it is a Killing field.

**Remark.** There are no more new Killing fields in  $M$ , since the canonical connection is unique (unless  $M$  is round sphere, or a Lie group, with a bi-invariant metric). This is by making use of the so-called *skew-torsion holonomy theorem* (O.- Reggiani, Crelle's 2011)

$$\text{Lie}(I(M)) = \mathfrak{g} \oplus \hat{\mathfrak{m}}_0$$

(direct sum of ideals).

Let  $\hat{w}$  denote the  $G$ -invariant vector with  $\hat{w}(q) = w \in \mathfrak{m}_0$ . Such a field is parallel with respect to the canonical connection. In fact, any  $G$ -invariant tensor is  $\nabla^c$ -parallel. Then, for any  $v \in \mathfrak{m} \simeq T_p M$ ,  $w \in \mathfrak{m}_0$ ,

$$(\nabla_v \hat{w})_q = D_v w$$

Observe, since  $D$  is totally skew, that  $\hat{w}$  satisfies the Killing equation and hence it is a Killing field.

**Remark.** There are no more new Killing fields in  $M$ , since the canonical connection is unique (unless  $M$  is round sphere, or a Lie group, with a bi-invariant metric). This is by making use of the so-called *skew-torsion holonomy theorem* (O.- Reggiani, Crelle's 2011)

$$\text{Lie}(I(M)) = \mathfrak{g} \oplus \hat{\mathfrak{m}}_0$$

(direct sum of ideals).

Let  $\hat{w}$  denote the  $G$ -invariant vector with  $\hat{w}(q) = w \in \mathfrak{m}_0$ . Such a field is parallel with respect to the canonical connection. In fact, any  $G$ -invariant tensor is  $\nabla^c$ -parallel. Then, for any  $v \in \mathfrak{m} \simeq T_p M$ ,  $w \in \mathfrak{m}_0$ ,

$$(\nabla_v \hat{w})_q = D_v w$$

Observe, since  $D$  is totally skew, that  $\hat{w}$  satisfies the Killing equation and hence it is a Killing field.

**Remark.** There are no more new Killing fields in  $M$ , since the canonical connection is unique (unless  $M$  is round sphere, or a Lie group, with a bi-invariant metric). This is by making use of the so-called *skew-torsion holonomy theorem* (O.- Reggiani, Crelle's 2011)

$$\text{Lie}(I(M)) = \mathfrak{g} \oplus \hat{\mathfrak{m}}_0$$

(direct sum of ideals).



On the other hand, from the previous formulae,

$$(\nabla_v \tilde{w})_q = -D_v w$$

Hence the Killing field

$$\tilde{v} = \frac{1}{2}\tilde{v} + \frac{1}{2}\hat{v}$$

satisfies

$$(\nabla \tilde{v})_q = 0, \quad \tilde{v}(q) = v$$

Therefore,  $\mathfrak{m}_0 \subset \mathfrak{s}_q$ , and thus the distribution of symmetry is non-trivial.

On the other hand, from the previous formulae,

$$(\nabla_v \tilde{w})_q = -D_v w$$

Hence the Killing field

$$\tilde{v} = \frac{1}{2}\tilde{v} + \frac{1}{2}\hat{v}$$

satisfies

$$(\nabla \tilde{v})_q = 0, \quad \tilde{v}(q) = v$$

Therefore,  $\mathfrak{m}_0 \subset \mathfrak{s}_q$ , and thus the distribution of symmetry is non-trivial.

On the other hand, from the previous formulae,

$$(\nabla_v \tilde{w})_q = -D_v w$$

Hence the Killing field

$$\tilde{v} = \frac{1}{2}\tilde{v} + \frac{1}{2}\tilde{v}$$

satisfies

$$(\nabla \tilde{v})_q = 0, \quad \tilde{v}(q) = v$$

Therefore,  $\mathfrak{m}_0 \subset \mathfrak{s}_q$ , and thus the distribution of symmetry is non-trivial.

On the other hand, from the previous formulae,

$$(\nabla_v \tilde{w})_q = -D_v w$$

Hence the Killing field

$$\bar{v} = \frac{1}{2} \tilde{v} + \frac{1}{2} \hat{v}$$

satisfies

$$(\nabla \bar{v})_q = 0, \quad \bar{v}(q) = v$$

Therefore,  $\mathfrak{m}_0 \subset \mathfrak{s}_q$ , and thus the distribution of symmetry is non-trivial.

On the other hand, from the previous formulae,

$$(\nabla_v \tilde{w})_q = -D_v w$$

Hence the Killing field

$$\bar{v} = \frac{1}{2} \tilde{v} + \frac{1}{2} \hat{v}$$

satisfies

$$(\nabla \bar{v})_q = 0, \quad \bar{v}(q) = v$$

Therefore,  $\mathfrak{m}_0 \subset \mathfrak{s}_q$ , and thus the distribution of symmetry is non-trivial.

On the other hand, from the previous formulae,

$$(\nabla_v \tilde{w})_q = -D_v w$$

Hence the Killing field

$$\bar{v} = \frac{1}{2} \tilde{v} + \frac{1}{2} \hat{v}$$

satisfies

$$(\nabla \bar{v})_q = 0, \quad \bar{v}(q) = v$$

Therefore,  $\mathfrak{m}_0 \subset \mathfrak{s}_q$ , and thus the distribution of symmetry is non-trivial.

On the other hand, from the previous formulae,

$$(\nabla_v \tilde{w})_q = -D_v w$$

Hence the Killing field

$$\bar{v} = \frac{1}{2} \tilde{v} + \frac{1}{2} \hat{v}$$

satisfies

$$(\nabla \bar{v})_q = 0, \quad \bar{v}(q) = v$$

Therefore,  $\mathfrak{m}_0 \subset \mathfrak{s}_q$ , and thus the distribution of symmetry is non-trivial.

On the other hand, from the previous formulae,

$$(\nabla_v \tilde{w})_q = -D_v w$$

Hence the Killing field

$$\bar{v} = \frac{1}{2} \tilde{v} + \frac{1}{2} \hat{v}$$

satisfies

$$(\nabla \bar{v})_q = 0, \quad \bar{v}(q) = v$$

Therefore,  $\mathfrak{m}_0 \subset \mathfrak{s}_q$ , and thus the distribution of symmetry is non-trivial.



**Theorem** (O.-Reggiani-Tamaru). Let  $M$  be a simply connected compact homogeneous naturally reductive space. Then the index of symmetry of  $M$  coincides with the dimension of the fixed vectors of the isotropy of the group of transvections.

**Corollary** (O.-Reggiani-Tamaru) Let  $M = G/H$  be a simply connected compact normal homogeneous space. Then the index of symmetry of  $M$  coincides with the dimension of the fixed vectors of the isotropy  $H$ .

**Theorem** (O.-Reggiani-Tamaru). Let  $M$  be a simply connected compact homogeneous naturally reductive space. Then the index of symmetry of  $M$  coincides with the dimension of the fixed vectors of the isotropy of the group of transvections.

**Corollary** (O.-Reggiani-Tamaru) Let  $M = G/H$  be a simply connected compact normal homogeneous space. Then the index of symmetry of  $M$  coincides with the dimension of the fixed vectors of the isotropy  $H$ .

## Open questions.

Assume that  $M^n$  is a compact simply connected irreducible Riemannian manifold with a positive index of symmetry.

Introduction

The index of  
symmetry

The dimension  
bound

Examples

Open questions

## Open questions.

Assume that  $M^n$  is a compact simply connected irreducible Riemannian manifold with a positive index of symmetry.

## Open questions.

Assume that  $M^n$  is a compact simply connected irreducible Riemannian manifold with a positive index of symmetry.

- Are the leaves of the distribution of symmetry compact (or equivalently, is the flat factor compact?).

- Are the leaves of the distribution of symmetry compact (or equivalently, is the flat factor compact?).

- Are the leaves of the distribution of symmetry compact (or equivalently, is the flat factor compact?).



- Are the leaves of the distribution of symmetry compact (or equivalently, is the flat factor compact?).

- Are the leaves of the distribution of symmetry compact (or equivalently, is the flat factor compact?).

– If  $n > 3$ , does the metric on  $M$  projects down to the quotient by the symmetric foliation? (if the space is locally irreducible) The situation, for  $n > 3$ , seems to be very rigid.

– Find new examples.

– Classify the case of co-index of symmetry equals to 3 and 4 (in which case the dimension is at most 6 or 10).

Or, more generally, classify the compact simply connected, irreducible, Riemannian homogeneous manifolds with a positive index of symmetry.

– If  $n > 3$ , does the metric on  $M$  projects down to the quotient by the symmetric foliation? (if the space is locally irreducible) The situation, for  $n > 3$ , seems to be very rigid.

– Find new examples.

– Classify the case of co-index of symmetry equals to 3 and 4 (in which case the dimension is at most 6 or 10).

Or, more generally, classify the compact simply connected, irreducible, Riemannian homogeneous manifolds with a positive index of symmetry.

– If  $n > 3$ , does the metric on  $M$  projects down to the quotient by the symmetric foliation? (if the space is locally irreducible) The situation, for  $n > 3$ , seems to be very rigid.

– Find new examples.

– Classify the case of co-index of symmetry equals to 3 and 4 (in which case the dimension is at most 6 or 10).

Or, more generally, classify the compact simply connected, irreducible, Riemannian homogeneous manifolds with a positive index of symmetry.

– If  $n > 3$ , does the metric on  $M$  projects down to the quotient by the symmetric foliation? (if the space is locally irreducible) The situation, for  $n > 3$ , seems to be very rigid.

– Find new examples.

– Classify the case of co-index of symmetry equals to 3 and 4 (in which case the dimension is at most 6 or 10).

Or, more generally, classify the compact simply connected, irreducible, Riemannian homogeneous manifolds with a positive index of symmetry.

– If  $n > 3$ , does the metric on  $M$  projects down to the quotient by the symmetric foliation? (if the space is locally irreducible) The situation, for  $n > 3$ , seems to be very rigid.

– Find new examples.

– Classify the case of co-index of symmetry equals to 3 and 4 (in which case de dimension is at most 6 or 10).

Or, more generally, classify the compact simply connected, irreducible, Riemannian homogeneous manifolds with a positive index of symmetry.

– If  $n > 3$ , does the metric on  $M$  projects down to the quotient by the symmetric foliation? (if the space is locally irreducible) The situation, for  $n > 3$ , seems to be very rigid.

– Find new examples.

– Classify the case of co-index of symmetry equals to 3 and 4 (in which case the dimension is at most 6 or 10).

Or, more generally, classify the compact simply connected, irreducible, Riemannian homogeneous manifolds with a positive index of symmetry.